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*Includes Part  
1A: Books and  
Part 1B:  
Pamphlets,  
Serials and  
Contributions  
to Periodicals  
Interface Age*

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*Commerce*

*Business Daily*

*The Next*

*Sustainability*

*Wave*

*Foodservice*

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*Guide*

A timely and  
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champions wanting

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to promote "deeper  
green" companies.

The New Century  
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Patent and

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This book will teach you everything you need to know to start using SOLIDWORKS 2016 with easy to understand, step-by-step tutorials. This book features a simple robot design used as a project

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throughout the book. You will learn to model parts, create assemblies, run simulations and even create animations of your robot design. No previous experience with Computer Aided Design (CAD) is

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needed since  
this book starts  
at an  
introductory  
level. The  
author begins by  
getting you  
familiar with  
the SOLIDWORKS  
interface and  
its basic tools  
right away. You  
will start by  
learning to

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model simple  
robot parts and  
before long you  
will graduate to  
creating more  
complex parts  
and multi-view  
drawings. Along  
the way you will  
learn the  
fundamentals of  
parametric  
modeling through  
the use of

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geometric constraints and relationships. You will also become familiar with many of SOLIDWORKS powerful tools and commands that enable you to easily construct complex features in your models.



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Also included is coverage of gears, gear trains and spur gear creation using SolidWorks. This book continues by examining the different mechanisms commonly used in walking robots. You will learn

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the basic types  
of planar four-  
bar linkages  
commonly used in  
mechanical  
designs and how  
to use the  
GeoGebra Dynamic  
Geometry  
software to  
simulate and  
analyze 2D  
linkages. Using  
the knowledge

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you gained about linkages and mechanism, you will learn how to modify your robot and change its behavior by modifying or creating new parts. In the final chapter of this book you learn how to combine all the

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robot parts into assemblies and then run motion analysis. You will finish off your project by creating 3D animations of your robot in action. There are many books that show you how to perform individual tasks

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with SOLIDWORKS,  
but this book  
takes you  
through an  
entire project  
and shows you  
the complete  
engineering  
process. By the  
end of this book  
you will have  
modeled and  
assembled nearly  
all the parts

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that make up the  
TAMIYA

Mechanical Tiger  
and can start  
building your  
own robot.

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The Wall Street  
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Building  
Boardroom Buy-  
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Security  
Management  
InfoWorld*

## Access Free Spur Menu Spurcorp

This book will teach you everything you need to know to start using SolidWorks 2014 with easy to understand, step-by-step tutorials. This book features a simple robot design used as a project throughout the book. You will learn to model parts, create

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assemblies, run simulations and even create animations of your robot design.

No previous experience with Computer Aided Drafting (CAD) is needed since this book starts at an introductory level. The author begins by getting you familiar

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with the SolidWorks interface and its basic tools right away. You will start by learning to model simple robot parts and before long you will graduate to creating more complex parts and multi-view drawings. Along the way you will learn the

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fundamentals of parametric modeling through the use of geometric constraints and relationships. You will also become familiar with many of SolidWorks's powerful tools and commands that enable you to easily construct complex

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features in your models. Also included is coverage of gears, gear trains and spur gear creation using SolidWorks. This book continues by examining the different mechanisms commonly used in walking robots. You

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will learn the basic types of planar four-bar linkages commonly used in mechanical designs and how to use the GeoGebra Dynamic Geometry software to simulate and analyze 2D linkages. Using the knowledge you gained about linkages and

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mechanism, you will learn how to modify your robot and change its behavior by modifying or creating new parts. In the final chapter of this book you learn how to combine all the robot parts into assemblies and then run motion analysis. You will



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finish off your project by creating 3D animations of your robot in action. There are many books that show you how to perform individual tasks with SolidWorks, but this book takes you through an entire project and shows you the complete

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engineering process.  
By the end of this  
book you will have  
modeled and  
assembled nearly all  
the parts that make  
up the TAMIYA®  
Mechanical Tiger  
and can start  
building your own  
robot.

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