Sliding Mode Control And Observation Control Engineering Hardcover June 1 2013

This book compiles recent developments on sliding mode control theory and its applications. Each chapter presented in the book proposes new dimension in the sliding mode control theory such as higher order sliding mode control, event triggered sliding mode control, networked control, higher order discrete-time sliding mode control and sliding mode control for multi-agent systems. Special emphasis has been given to practical solutions to design involving new types of sliding mode control. This book is a reference guide for graduate students and researchers working in the domain for designing sliding mode controllers. The book is also useful to professional engineers working in the field to design robust controllers for various applications.
The sliding mode control paradigm has become a mature technique for the design of robust controllers for a wide class of systems including nonlinear, uncertain and time-delayed systems. This book is a collection of plenary and invited talks delivered at the 12th IEEE International Workshop on Variable Structure System held at the Indian Institute of Technology, Mumbai, India in January 2012. After the workshop, these researchers were invited to develop book chapters for this edited collection in order to reflect the latest results and open research questions in the area. The contributed chapters have been organized by the editors to reflect the various themes of sliding mode control which are the current areas of theoretical research and applications focus; namely articulation of the fundamental underpinning theory of the sliding mode design paradigm, sliding modes for decentralized system representations, control of time-delay systems, the higher order sliding mode concept, results applicable to nonlinear and underactuated systems, sliding mode observers, discrete sliding mode control together with cutting edge research contributions in the application of the sliding mode concept to real world problems. This book provides the reader with a clear and complete picture of the current trends in Variable Structure Systems and Sliding Mode Control Theory.
This two-volume set of LNCS 11643 and LNCS 11644 constitutes – in conjunction with the volume LNAI 11645 – the refereed proceedings of the 15th International Conference on Intelligent Computing, ICIC 2019, held in Nanchang, China, in August 2019. The 217 full papers of the three proceedings volumes were carefully reviewed and selected from 609 submissions. The ICIC theme unifies the picture of contemporary intelligent computing techniques as an integral concept that highlights the trends in advanced computational intelligence and bridges theoretical research with applications. The theme for this conference is "Advanced Intelligent Computing Methodologies and Applications." Papers related to this theme are especially solicited, including theories, methodologies, and applications in science and technology.
This book describes recent advances in the theory, properties, methods and applications of SMC, including a discussion about the advantages and disadvantages of different SMC algorithms.
Applications of Sliding Mode Control in Science and Engineering
Theory And Applications
Recent Advances in Sliding Modes: From Control to Intelligent Mechatronics
Advances in Variable Structure Systems and Sliding Mode Control—Theory and Applications
A Multirate Output Feedback Approach
Lectures given at the C.I.M.E. Summer School held in Cetraro, Italy, June 19-29, 2004

This book is devoted to control of finite and infinite dimensional processes with continuous-time and discrete time control, focusing on suppression problems and new methods of adaptation applicable for systems with sliding motions only. Special mathematical methods are needed for all the listed control tasks. These methods are addressed in the initial chapters, with coverage of the definition of the multidimensional sliding modes, the derivation of the differential equations of those motions, and the existence conditions. Subsequent chapters discusses various areas of further research. The book reflects the consensus view of the authors regarding the current status of SMC theory. It is addressed to a broad spectrum of engineers and theoreticians working in diverse areas of control theory and applications. It is well suited for use in graduate and postgraduate courses in such university programs as Electrical Engineering, Control of Nonlinear Systems, and Mechanical Engineering.
The development of computer software for nonlinear control systems has provided many benefits for teaching, research, and the development of control systems design. MATLAB is considered the dominant software platforms for linear and nonlinear control systems analysis. This book provides an easy way to learn nonlinear control systems such as feedback linearization technique and Sliding mode control (Structure variable control) which are one of the most used techniques in nonlinear control dynamical systems; therefore teachers-students and researchers are all in need to handle such techniques; and since they are too difficult for them to handle such nonlinear controllers especially for a more complicated systems such as induction motor, satellite, and vehicles dynamical models. Thus, this document it is an excellent resource for learning the principle of feedback linearization and sliding mode techniques in an easy and simple way: Provides a briefs description of the feedback linearization and sliding mode control strategies Includes a simple method on how to determine the right and appropriate controller (P-PI-PID) for feedback linearization control strategy. A Symbolic MATLAB Based function for finding the feedback linearization and sliding mode controllers are developed and tested using several examples. A simple method for finding the approximate sliding mode controller parameters is introduced Where the program used to construct the nonlinear controller uses symbolic computations; such that the user should provide the program with the necessary functions f(x), g(x) and h(x) using the symbolic library.
Currently, the modelling and control of mechatronic and robotic systems is an open and challenging field of investigation in both industry and academia. The book encompasses the kinematic and dynamic modelling, analysis, design, and control of mechatronic and robotic systems, with the scope of improving their performance, as well as simulating and testing novel devices and control architectures. A broad range of disciplines and topics are included, such as robotic manipulation, mobile systems, cable-driven robots, wearable and rehabilitation devices, variable stiffness safety-oriented mechanisms, optimization of robot performance, and energy-saving systems.
This unique book fulfils the definite need for an accessible book on variable structure systems and also provides the very latest results in research on this topic. Divided into three parts - basics of sliding mode control, new trends in sliding mode control, and applications of sliding mode control - the book contains many numerical design examples, so that readers can quickly understand the design methodologies and their applications to practical problems. Primarily aimed at students and researchers in the field, the book will also be useful for practising control engineers.
Discrete-Time Stochastic Sliding Mode Control Using Functional Observation
From Theory to Practice
A New Approach to Control System Design
Intelligent Computing Theories and Application
Variable Structure Systems
Advances in Control Techniques for Smart Grid Applications

The lectures gathered in this volume present some of the different aspects of Mathematical Control Theory. Adopting the point of view of Geometric Control Theory and of Nonlinear Control Theory, the lectures focus on some aspects of the Optimization and Control of nonlinear, not necessarily smooth, dynamical systems. Specifically, three of the five lectures discuss respectively: logic-based switching control, sliding mode control and the input to the state stability paradigm for the control and stability of nonlinear systems. The remaining two lectures are devoted to Optimal Control: one investigates the connections between Optimal Control Theory, Dynamical Systems and Differential Geometry, while the second presents a very general version, in a non-smooth context, of the Pontryagin Maximum Principle. The arguments of the whole volume are self-contained and are directed to everyone working in Control Theory. They offer a sound presentation of the methods employed in the control and optimization of nonlinear dynamical systems.
This concise book covers modern sliding mode control theory. The authors identify key contributions defining the theoretical and applicative state-of-the-art of the sliding mode control theory and the most promising trends of the ongoing research activities.
This volume is dedicated to Professor Okyay Kaynak to commemorate his life time impactful research and scholarly achievements and outstanding services to profession. The 21 invited chapters have been written by leading researchers who, in the past, have had association with Professor Kaynak as either his students and associates or colleagues and collaborators. The focal theme of the volume is the Sliding Modes covering a broad scope of topics from theoretical investigations to their significant applications from Control to Intelligent Mechatronics.
To meet the increasing demand of electrical power, the use of renewable energy-based smart grid is attracting significant attention in recent years throughout the world. The high penetration of renewable power in the smart grids is growing its importance due to its non-finishing, reusable, reliable, sustainable, lower cost, and available characteristics. The renewable energy-based smart grid technology may mitigate the increasing energy demands effectively and efficiently without hampering the environment. But the uncertain nature of renewable sources largely affects the operation of the smart grid by un-stabling the voltage and frequency that may introduces power quality and reliability problems, which requires special control techniques. This book investigates the challenges in controlling renewable energy-based smart grids and proposes different control techniques to control the voltage and frequency effectively to improve the power quality and reliability of the power grids. This book is a valuable resource for readers interested in practical solutions in smart grids and renewable energy systems.
Control and Observation of Electric Machines by Sliding Modes
Recent Trends in Sliding Mode Control
From Principles to Implementation
Sliding Mode Control
Concept, Theory and Implementation
15th International Conference, ICIC 2019, Nanchang, China, August 3 – 6, 2019, Proceedings, Part III
The sliding mode control methodology has proven effective in dealing with complex dynamical systems affected by disturbances, uncertainties and unmodeled dynamics. Robust control technology based on this methodology has been applied to many real-world problems, especially in the areas of aerospace control, electric power systems, electromechanical systems, and robotics. Sliding Mode Control and Observation represents the first textbook that starts with classical sliding mode control techniques and progresses toward newly developed higher-order sliding mode control and observation algorithms and their applications. The present volume addresses a range of sliding mode control issues, including: *Conventional sliding mode controller and observer design *Second-order sliding mode controllers and differentiators *Frequency domain analysis of conventional and second-order sliding mode controllers *Higher-order sliding mode controllers and differentiators *Higher-order sliding mode observers *Sliding mode disturbance observer based control *Numerous applications, including reusable launch vehicle and satellite formation control, blood glucose regulation, and car steering control are used as case studies Sliding Mode Control and Observation is aimed at graduate students with a basic knowledge of classical control theory and some knowledge of state-space methods and nonlinear systems, while being of interest to a wider audience of graduate students in electrical/mechanical/aerospace engineering and applied mathematics, as well as researchers in electrical, computer, chemical, civil, mechanical, aeronautical, and industrial engineering, applied mathematicians, control engineers, and physicists. Sliding Mode Control and Observation provides the necessary tools for graduate students, researchers and engineers to robustly control complex and uncertain nonlinear dynamical systems. Exercises provided at the end of each chapter make this an ideal text for an advanced course taught in control theory.
Sliding Mode Control Using MATLAB provides many sliding mode controller design examples, along with simulation examples and MATLAB® programs. Following the review of sliding mode control, the book includes sliding mode control for continuous systems, robust adaptive sliding mode control, sliding mode control for underactuated systems, backstepping, and dynamic surface sliding mode control, sliding mode control based on filter and observer, sliding mode control for discrete systems, fuzzy sliding mode control, neural network sliding mode control, and sliding mode control for robot manipulators. The contents of each chapter are independent, providing readers with information they can use for their own needs. It is suitable for the readers who work on mechanical and electronic engineering, electrical automation engineering, etc., and can also be used as a teaching reference for universities. Provides many sliding mode controller design examples to help readers solve their research and design problems Includes various, implementable, robust sliding mode control design solutions from engineering applications Provides the simulation examples and MATLAB programs for each sliding mode control algorithm
The book is devoted to systems with discontinuous control. The study of discontinuous dynamic systems is a multifacet problem which embraces mathematical, control theoretic and application aspects. Times and again, this problem has been approached by mathematicians, physicists and engineers, each profession treating it from its own positions. Interestingly, the results obtained by specialists in different disciplines have almost always had a significant effect upon the development of the control theory. It suffices to mention works on the theory of oscillations of discontinuous nonlinear systems, mathematical studies in ordinary differential equations with discontinuous righthand parts or variational problems in nonclassic statements. The unremitting interest to discontinuous control systems enhanced by their effective application to solution of problems most diverse in their physical nature and functional purpose is, in the author's opinion, a cogent argument in favour of the importance of this area of studies. It seems a useful effort to consider, from a control theoretic viewpoint, the mathematical and application aspects of the theory of discontinuous dynamic systems and determine their place within the scope of the present-day control theory. The first attempt was made by the author in 1975-1976 in his course on "The Theory of Discontinuous Dynamic Systems" and "The Theory of Variable Structure Systems" read to post-graduates at the University of Illinois, USA, and then presented in 1978-1979 at the seminars held in the Laboratory of Systems with Discontinous Control at the Institute of Control Sciences in Moscow.
This edited monograph provides a comprehensive and in-depth analysis of sliding mode control, focusing on event-triggered implementation. The technique allows to prefix the steady-state bounds of the system, and this is independent of any boundary disturbances. The idea of event-triggered SMC is developed for both single input / single output and multi-input / multi-output linear systems. Moreover, the reader learns how to apply this method to nonlinear systems. The book primarily addresses research experts in the field of sliding mode control, but the book may also be beneficial for graduate students.
Control of Marine Vehicles
17th International Conference, ICIC 2021, Shenzhen, China, August 12–15, 2021, Proceedings, Part II
New Perspectives and Applications
Sliding Modes in Control and Optimization
Discrete-time Sliding Mode Control
Variable-Structure Systems and Sliding-Mode Control

This two-volume set of LNCS 12836 and LNCS 12837 constitutes - in conjunction with the volume LNAI 12838 - the refereed proceedings of the 17th International Conference on Intelligent Computing, ICIC 2021, held in Shenzhen, China in August 2021. The 192 full papers of the three proceedings volumes were carefully reviewed and selected from 458 submissions. The ICIC theme unifies the picture of contemporary intelligent computing techniques as an integral concept that highlights the trends in advanced computational intelligence and bridges theoretical research with applications. The theme for this conference is "Advanced Intelligent Computing Methodologies and Applications." The papers are organized in the following subsections: Intelligent Computing in Computer Vision, Intelligent Control and Automation, Intelligent Modeling Technologies for Smart Cities, Machine Learning, and Theoretical Computational Intelligence and Applications.
The book presents the newest results of the major world research groups working in the area of Variable Structure Systems and Sliding Mode Control (VSS/SMC). The research activity of these groups is coordinated by the IEEE Technical Committee on Variable Structure Systems (VSS) and Sliding Modes (SM). The presented results include the reports of the research groups collaborating in a framework of the Unión European Union – México project of Fondo de Cooperación Internacional en Ciencia y Tecnología (FONCICyT) 93302 titled "Automatization and Monitoring of Energy Production Processes via Sliding Mode Control". The book starts with the overview of the sliding mode control concepts and algorithms that were developed and discussed in the last two decades The research papers are combined in three sections: Part I: VSS and SM Algorithms and their Analysis Part II: SMC Design Part III: Applications of VSS and SMC The book will be of interests of engineers, researchers and graduate students working in the area of the control systems design. Novel mathematical theories and engineering concepts of control systems are rigorously discussed and supported by numerous applications to practical tasks.
Advanced Control Systems: Theory and Applications provides an overview of advanced research lines in control systems as well as in design, development and implementation methodologies for perspective control systems and their components in different areas of industrial and special applications. It consists of extended versions of the selected papers presented at the XXV International Conference on Automatic Control "Automatics 2018" (September 18-19, 2018, Lviv, Ukraine) which is the main Ukrainian Control Conference organized by Ukrainian Association on Automatic Control (National member organization of IFAC) and Lviv National University "Lvivska Politechnica." More than 100 papers were presented at the conference with topics including: mathematical problems of control, optimization and game theory; control and identification under uncertainty; automated control of technical, technological and biotechnical objects; controlling the aerospace craft, marine vessels and other moving objects; intelligent control and information processing; mechatronics and robotics; information measuring technologies in automation; automation and IT training of personnel; the Internet of things and the latest technologies. The book is divided into two main parts, the first concerning theory (7 chapters) and the second concerning applications (7 chapters) of advanced control systems. The first part "Advances in Theoretical Research on Automatic Control" consists of theoretical research results which deal with descriptor control impulsive delay systems, motion control in condition of conflict, inverse dynamic models, invariant relations in optimal control, robust adaptive control, bio-inspired algorithms, optimization of fuzzy control systems, and extremal routing problem with constraints and complicated cost functions. The second part "Advances in Control Systems Applications" is based on the chapters which consider different aspects of practical implementation of advanced control systems, in particular, special cases in determining the spacecraft position and attitude using computer vision system, the spacecraft orientation by information from a system of stellar sensors, control synthesis of rotational and spatial spacecraft motion at approaching stage of docking, intelligent algorithms for the automation of complex biotechnical objects, an automatic control system for the slow pyrolysis of organic substances with variable composition, simulation complex of hierarchical systems based on the foresight and cognitive modelling, and advanced identification of impulse processes in cognitive maps. The chapters have been structured to provide an easy-to-follow introduction to the topics that are addressed, including the most relevant references, so that anyone interested in this field can get started in the area. This book may be useful for researchers and students who are interested in advanced control systems.
This volume presents the theory of control systems with sliding mode applied to electrical motors and power converters. It demonstrates the methodology of control design and the original algorithms of control and observation. Practically all semiconductor devices are used in power converters, that feed electrical motors, as power switches. A switching mode offers myriad attractive, inherent properties from a control viewpoint, especially a sliding mode. Sliding mode control supplies high dynamics to systems, invariability of systems to changes of their parameters and of exterior loads in combination with simplicity of design. Unlike linear control, switching sliding mode control does not replace the control system, but uses the natural properties of the control plant system effectively to ensure high control quality. This is the first text that thoroughly describes the application of the highly theoretical control design approach to synchronous drives in practice. It examines in detail the different features of various types of synchronous motors and converters with regard to sliding mode control design. It further presents a detailed analysis of control issues and mechanical coordinate observation design for various types of synchronous motors, of power converters, and various drive control structures. It also discusses the digital implementation of control, observation and identification algorithms. The potential of sliding mode control and observation are moreover demonstrated in numerical and experimental results from real control plants. This work is intended for professionals and advanced students who work in the field of electric drive control. It is also recommended to experts in control theory application, who work with sliding modes for the control of electrical motors and power converters.
Advances and Applications in Sliding Mode Control systems
Observation and Control
Sliding Mode Control and Observation
Advances in Sliding Mode Control
Applications of Sliding Mode Control
Theory and Application

This textbook offers a comprehensive introduction to the control of marine vehicles, from fundamental to advanced concepts, including robust control techniques for handling model uncertainty, environmental disturbances, and actuator limitations. Starting with an introductory chapter that extensively reviews automatic control and dynamic modeling techniques for ocean vehicles, the first part of the book presents in-depth information on the analysis and control of linear time invariant systems. The concepts discussed are developed progressively, providing a basis for understanding more complex techniques and stimulating readers' intuition. In addition, selected examples illustrating the main concepts, the corresponding MATLAB® code, and problems are included in each chapter. In turn, the second part of the book offers comprehensive coverage on the stability and control of nonlinear systems. Following the same intuitive approach, it guides readers from the fundamentals to more advanced techniques, which culminate in integrator backstepping, adaptive and sliding mode control. Leveraging the author's considerable teaching and research experience, the book offers a good balance of theory and stimulating questions. Not only does it provide a valuable resource for

undergraduate and graduate students; it will also benefit practitioners who want to review the foundational concepts underpinning some of the latest advanced marine vehicle control techniques, for use in their own applications.
The main objective of this monograph is to present a broad range of well worked out, recent application studies as well as theoretical contributions in the field of sliding mode control system analysis and design. The contributions presented here include new theoretical developments as well as successful applications of variable structure controllers primarily in the field of power electronics, electric drives and motion steering systems. They enrich the current state of the art, and motivate and encourage new ideas and solutions in the sliding mode control area.
Apply Sliding Mode Theory to Solve Control Problems Interest in SMC has grown rapidly since the first edition of this book was published. This second edition includes new results that have been achieved in SMC throughout the past decade relating to both control design methodology and applications. In that time, Sliding Mode Control (SMC) has continued to gain increasing importance as a universal design tool for the robust control of linear and nonlinear electro-mechanical systems. Its strengths result from its simple, flexible, and highly cost-effective approach to design and implementation. Most importantly, SMC promotes inherent order reduction and allows for the direct incorporation of robustness against system uncertainties and disturbances. These qualities lead to dramatic improvements in stability and help enable the design of high-performance control systems at low cost. Written by three of the most respected experts in the field, including one of its originators, this updated edition of Sliding Mode Control in Electro-Mechanical Systems reflects developments in the field over the past decade. It builds on the solid fundamentals presented in the first edition to promote a deeper understanding of the conventional SMC methodology, and it examines new design principles in order to broaden the application potential of SMC. SMC is particularly useful for the design of electromechanical systems because of its discontinuous structure. In fact, where the hardware of many electromechanical systems (such as electric motors) prescribes discontinuous inputs, SMC becomes the natural choice for direct implementation. This book provides a unique combination of theory, implementation issues, and examples of real-life applications reflective of the authors' own industry-leading work in the development of robotics, automobiles, and other technological breakthroughs.
In the formation of any control problem there will be discrepancies between the actual plant and the mathematical model for controller design. Sliding mode control theory seeks to produce controllers to over some such mismatches. This text provides the reader with a grounding in sliding mode control and is appropriate for the graduate with a basic knowledge of classical control theory and some knowledge of state-space methods. From this basis, more advanced theoretical results are developed. Two industrial case studies, which present the results of sliding mode controller implementations, are used to illustrate the successful practical application theory.
Gedanken vom Schlaf und den Träumen
Sliding Mode Control In Engineering
Hybrid Dynamical Systems
Sliding Mode Control for Synchronous Electric Drives
Emerging Trends in Sliding Mode Control
Control Theory in Engineering

Provides comprehensive coverage of the most recent developments in the theory of non-Archimedean pseudo-differential equations and its application to stochastics and mathematical physics--offering current methods of construction for stochastic processes in the field of p-adic numbers and related structure theory for parabolic equat

Gathering 20 chapters contributed by respected experts, this book reports on the latest advances in and applications of sliding mode control in science and engineering. The respective chapters address applications of sliding mode control in the broad areas of chaos theory, robotics, electrical engineering, phy engineering, memristors, mechanical engineering, environmental engineering, finance, and biology. Special emphasis has been given to papers that offer practical solutions, and which examine design and modeling involving new types of sliding mode control such as higher order sliding mode control, terminal control, super-twisting sliding mode control, and integral sliding mode control. This book serves as a unique reference guide to sliding mode control and its recent applications for graduate students and researchers with a basic knowledge of electrical and control systems engineering.

This book is a collection of contributions defining the state of current knowledge and new trends in hybrid systems – systems involving both continuous dynamics and discrete events – as described by the work of several well-known groups of researchers. Hybrid Dynamical Systems presents theoretical advan diagnosability, observability and stabilization for various classes of system. Continuous and discrete state estimation and self-triggering control of nonlinear systems are advanced. The text employs various methods, among them, high-order sliding modes, Takagi–Sugeno representation and sampled-data swit ends. The many applications of hybrid systems from power converters to computer science are not forgotten; studies of flexible-joint robotic arms and – as representative biological systems – the behaviour of the human heart and vasculature, demonstrate the wide-ranging practical significance of control in hy cross-disciplinary origins of study in hybrid systems are evident. Academic researchers and graduate students interested in hybrid and switched systems need look no further than Hybrid Dynamical Systems for a single source which will bring them up to date with work in this area from around the world.

This book extrapolates many of the concepts that are well defined for discrete-time deterministic sliding-mode control for use with discrete-time stochastic systems. It details sliding-function designs for various categories of linear time-invariant systems and its application for control. The resulting sliding-mode c robustness issues and the functional-observer approach reduces the observer order substantially. Sliding-mode control (SMC) is designed for discrete-time stochastic systems, extended so that states lie within a specified band, and able to deal with incomplete information. Functional-observer-based SMC is d clauses of stochastic systems: discrete-time; discrete-time with delay; state time-delayed; and those with parametric uncertainty. Stability considerations arising because of parametric uncertainty are taken into account and, where necessary, the effects of unmatched uncertainties mitigated. A simulation examp the use of the functional-observer approach to SMC design. Discrete-Time Stochastic Sliding-Mode Control Using Functional Observation will interest all researchers working in sliding-mode control and will be of particular assistance to graduate students in understanding the changes in design philosophy that changing from continuous- to discrete-time systems. It helps to pave the way for further progress in applications of discrete-time SMC.

Road Map for Sliding Mode Control Design
Modelling and Control of Mechatronic and Robotic Systems
Advanced Control Systems - Theory and Applications
Intelligent Computing Methodologies
State of the Art
Event-Triggered Sliding Mode Control

The subject matter of this book ranges from new control design methods to control theory applications in electrical and mechanical engineering and computers. The book covers certain aspects of control theory, including new methodologies, techniques, and applications. It promotes control theory in practical applications of these engineering domains and shows the way to disseminate researchers' contributions in the field. This project presents applications that improve the properties and performance of control systems in analysis and design using a higher technical level of scientific attainment. The authors have included worked examples and case studies resulting from their research in the field. Readers will benefit from new solutions and answers to questions related to the emerging realm of control theory in engineering applications and its implementation.

This book reflects the latest developments in variable structure systems (VSS) and sliding mode control (SMC), highlighting advances in various branches of the VSS/SMC field, e.g., from conventional SMC to high-order SMC, from the continuous-time domain to the discrete-time domain, from theories to applications, etc. The book consists of three parts and 16 chapters: in the first part, new VSS/SMC algorithms are proposed and their properties are analyzed, while the second focuses on the use of VSS/SMC techniques to solve a variety of control problems; the third part examines the applications of VSS/SMC to real-time systems. The book introduces postgraduates and researchers to the state-of-the-art in VSS/SMC field, including the theory, methodology, and applications. Relative academic disciplines include Automation, Mathematics, Electrical Engineering, Mechanical Engineering, Instrument Science and Engineering, Electronic Engineering, Computer Science and Technology, Transportation Engineering, Energy and Power Engineering, etc.

Sliding Mode Control and ObservationSpringer Science & Business Media

Sliding mode control is a simple and yet robust control technique, where the system states are made to confine to a selected subset. With the increasing use of computers and discrete-time samplers in controller implementation in the recent past, discrete-time systems and computer based control have become important topics. This monograph presents an output feedback sliding mode control philosophy which can be applied to almost all controllable and observable systems, while at the same time being simple enough as not to tax the computer too much. It is shown that the solution can be found in the synergy of the multirate output sampling concept and the concept of discrete-time sliding mode control.

Sliding Mode Control in Electro-Mechanical Systems
Sliding Modes after the first Decade of the 21st Century
Nonlinear Control Systems using MATLAB®
Sliding Mode Control Using MATLAB
Sliding Mode Control Methodology in the Applications of Industrial Power Systems

This book describes the advances and applications in Sliding mode control (SMC) which is widely used as a powerful method to tackle uncertain nonlinear systems. The book is organized into 21 chapters which have been organised by the editors to reflect the various themes of sliding mode control. The book provides the reader with a broad range of material from first principles up to the current state of the art in the area of SMC and observation presented in a clear, matter-of-fact style. As such it is appropriate for graduate students with a basic knowledge of classical control theory and some knowledge of state-space methods and nonlinear systems. The resulting design procedures are emphasized using Matlab/Simulink software.
This book presents essential studies and applications in the context of sliding mode control, highlighting the latest findings from interdisciplinary theoretical studies, ranging from computational algorithm development to representative applications. Readers will learn how to easily tailor the techniques to accommodate their ad hoc applications. To make the content as accessible as possible, the book employs a clear route in each paper, moving from background to motivation, to quantitative development (equations), and lastly to case studies/illustrations/tutorials (simulations, experiences, curves, tables, etc.). Though primarily intended for graduate students, professors and researchers from related fields, the book will also benefit engineers and scientists from industry.
The book covers the latest theoretical results and sophisticated applications in the field of variable-structure systems and sliding-mode control. This book is divided into four parts. Part I discusses new higher-order sliding-mode algorithms, including new homogeneous controllers and differentiators. Part II then explores properties of continuous sliding-mode algorithms, such as saturated feedback control, reaching time, and orbital stability. Part III is focused on the usage of variable-structure systems (VSS) controllers for solving other control problems, for example unmatched disturbances. Finally, Part IV discusses applications of VSS; these include applications within power electronics and vehicle platooning. Variable-structure Systems and Sliding-Mode Control will be of interest to academic researchers, students and practising engineers.
Abstract: The objective of this dissertation is to develop control and estimation methods for electric machines based on sliding mode control theory. Major attention is paid to two types of AC machines, i.e. the induction machine (IM) and the synchronous machine, including the permanent magnet synchronous machine (PMSM). This choice may be explained by the fact that AC drives are gradually superseding DC ones for many dynamic plants in modern industrial applications. The mothod proposed in this dissertation for both control and observation is the so-called sliding mode approach chosen because of its robustness and ability to reduce the order of the motion models. A further advantage is that the average values of discontinuous inputs (i.e. the so-called equivalent control) in sliding modes are algebraic functions of unknown state components and parameters. These equivalent control values can be easily obtained by using low pass filters and they are useful in calculation and estimation. As real-time computation costs continually decline, both mechanical robustness and economic considerations increasingly stimulate the replacement of mechanical sensors by software-based observation methods. These so-called sensorless systems are free of maintenance and exhibit high reliability and low cost. Elimination of encoders or resolvers on induction machine drives is a prime example. Due to the above reasons, many sensorless control schemes have been developed and described in literature. High order models of AC machines, nonlinearities in motion equations, uncertainties in model parameters and disturbances are the main obstacles hindering the development and rigorous mathematical analysis of such systems. However, their efficiency has been demonstrated by experiments and real applications. In contrast to conventional approaches, where control and observation are handled independently, the core idea of the approach proposed in this dissertation implies that they are treated as one interconnected system. This approach facilitates control system analysis and design since the speed is not an arbitrary time function any more but the solution to the known differential equations. As a result, the new structure of the observer is offered and the convergence of the observation is proven. There is one very important issue in the framework of the studies: varying of the model parameters in a wide range, in particular the rotor resistance, which may be within 30-40% because of heating. New approach is developed to identify speed, flux and rotor resistance simultaneously under the common assumption that the electromagnetic processes are faster than the mechanical ones. The developed control and estimation algorithms are tested experimentally for differenct types of induction machines.
nebst einem Schreiben, daß man ohne Kopf empfinden könne
Modern Sliding Mode Control Theory
Nonlinear and Optimal Control Theory

This book presents recent advanced techniques in sliding mode control and observer design for industrial power systems, focusing on their applications in polymer electrolyte membrane fuel cells and power converters. Readers will find not only valuable new fault detection and isolation techniques based on sliding mode control and observers, but also a number of robust control and estimation methodologies combined with fuzzy neural networks and extended state observer methods. The book also provides necessary experimental and simulation examples for proton exchange membrane fuel cell systems and power converter systems. Given its scope, it offers a valuable resource for undergraduate and graduate students, academics, scientists and engineers who are working in the field.
This volume presents the theory of control systems with sliding mode applied to electrical motors and power converters. It demonstrates the methodology of control design and the original algorithms of control and observation. Practically all semiconductor devices are used in power converters, that feed electrical motors, as power switches. A switch