

## Intelligent Control Aspects Of Fuzzy Logic And Neural Nets World Scientific Series In Robotics And Automated Systems

*This book is concerned with Intelligent Control methods and applications. The field of intelligent control has been expanded very much during the recent years and a solid body of theoretical and practical results are now available. These results have been obtained through the synergetic fusion of concepts and techniques from a variety of fields such as automatic control, systems science, computer science, neurophysiology and operational research. Intelligent control systems have to perform anthropomorphic tasks fully autonomously or interactively with the human under known or unknown and uncertain environmental conditions. Therefore the basic components of any intelligent control system include cognition, perception, learning, sensing, planning, numeric and symbolic processing, fault detection/repair, reaction, and control action. These components must be linked in a systematic, synergetic and efficient way. Predecessors of intelligent control are adaptive control, self-organizing control, and learning control which are well documented in the literature. Typical application examples of intelligent controls are intelligent robotic systems, intelligent manufacturing systems, intelligent medical systems, and intelligent space teleoperators. Intelligent controllers must employ both quantitative and qualitative information and must be able to cope with severe temporal and spatial variations, in addition to the fundamental task of achieving the desired transient and steady-state performance. Of course the level of intelligence required in each particular application is a matter of discussion between the designers and users. The current literature on intelligent control is increasing, but the information is still available in a sparse and disorganized way.*

*One of the attractions of fuzzy logic is its utility in solving many real engineering problems. As many have realised, the major obstacles in building a real intelligent machine involve dealing with random disturbances, processing large amounts of imprecise data, interacting with a dynamically changing environment, and coping with uncertainty. Neural-fuzzy techniques help one to solve many of these problems. Fuzzy Logic and Intelligent Systems reflects the most recent developments in neural networks and fuzzy logic, and their application in intelligent systems. In addition, the balance between theoretical work and applications makes the book suitable for both researchers and engineers, as well as for graduate students.*

*This book discusses systematic designs of stable adaptive fuzzy logic controllers employing hybridizations of Lyapunov strategy-based approaches/H<sup>∞</sup> theory-based approaches and contemporary stochastic optimization techniques. The text demonstrates how candidate stochastic optimization techniques like Particle swarm optimization (PSO), harmony search (HS) algorithms, covariance matrix adaptation (CMA) etc. can be utilized in conjunction with the Lyapunov theory/H<sup>∞</sup> theory to develop such hybrid control strategies. The goal of developing a series of such hybridization processes is to combine the strengths of both Lyapunov theory/H<sup>∞</sup> theory-based local search methods and stochastic optimization-based global search methods, so as to attain superior control algorithms that can simultaneously achieve desired asymptotic performance and provide improved transient responses. The book also demonstrates how these intelligent adaptive control algorithms can be effectively utilized in real-life applications such as in temperature control for air heater systems with transportation delay, vision-based navigation of mobile robots, intelligent control of robot manipulators etc.*

*This book describes intelligent control and its use in power electronic systems, specifically AC motor drives and uninterruptable power supply (UPS) systems. The book covers both the fundamentals of the subject and its practical applications. From the Foreword by Lofti A. Zadeh, Director of Berkeley Soft Computing Center, California: What is unusual about [this book] is that it starts with a description of more or less classical control techniques; moves on to modern control and state space techniques; addresses in detail the complex issues arising in the analysis and design of robust control; takes up digital signal processing controllers; and finally, presents a very insightful exposition of soft computing techniques and their application to advanced control of AC drives and UPS systems.*

**Principles, Techniques and Applications**

**Intelligent Control: Principles, Techniques and Applications**

**Control Systems, Robotics and AutomatiON - Volume XVII**

**Intelligent Adaptive Control**

**A Stochastic Optimization Based Adaptive Fuzzy Approach**

Great progresses have been made in the application of fuzzy set theory and fuzzy logic. Most remarkable area of application is 'fuzzy control', where fuzzy logic was first applied to plant control systems and its use is expanding to consumer products. Most of fuzzy control systems uses fuzzy inference with max-min or max-product composition, similar to the algorithm that first used by Mamdani in 1970s. Some algorithms are developed to refine fuzzy controls systems but the main part of algorithm stays the same. Triggered by the success of fuzzy control systems, other ways of applying fuzzy set theory are also investigated. They are usually referred to as 'fuzzy expert systems', and their purpose are to combine the idea of fuzzy theory with AI based approach toward knowledge processing. These approaches can be more generally viewed as 'fuzzy information processing', that is to bring fuzzy idea into information processing systems.

This book describes recent advances in the use of fuzzy logic for the design of hybrid intelligent systems based on nature-inspired optimization and their applications in areas such as intelligent control and robotics, pattern recognition, medical diagnosis, time series prediction and optimization of complex problems. Based on papers presented at the North American Fuzzy Information Processing Society Annual Conference (NAFIPS 2017), held in Cancun, Mexico from 16 to 18 October 2017, the book is divided into nine main parts, the first of which first addresses theoretical aspects, and proposes new concepts and algorithms based on type-1 fuzzy systems. The second part consists of papers on new concepts and algorithms for type-2 fuzzy systems, and on applications of type-2 fuzzy systems in diverse areas, such as time series prediction and pattern recognition. In turn, the third part contains papers that present enhancements to meta-heuristics based on fuzzy logic techniques describing new nature-inspired optimization algorithms that use fuzzy dynamic adaptation of parameters. The fourth part presents emergent intelligent models, which range from quantum algorithms to cellular automata. The fifth part explores applications of fuzzy logic in diverse areas of medicine, such as the diagnosis of hypertension and heart diseases. The sixth part describes new computational intelligence algorithms and their applications in different areas of intelligent control, while the seventh examines the use of fuzzy logic in different mathematic models. The eight part deals with a diverse range of applications of fuzzy logic, ranging from environmental to autonomous navigation, while the ninth covers theoretical concepts of fuzzy models

"Advances in Intelligent Control" is a collection of essays covering the latest research in the field. Based on a special issue of "The International Journal of Control", the book is arranged in two parts. Part one contains recent contributions of artificial neural networks to modelling and control. Part two concerns itself primarily with aspects of fuzzy logic in intelligent control, guidance and estimation, although some of the contributions either make direct equivalence relationships to neural networks or use hybrid methods where a neural network is used to develop the fuzzy rule base.

Soft computing is a consortium of computing methodologies that provide a foundation for the conception, design, and deployment of intelligent systems and aims to formalize the human ability to make rational decisions in an environment of uncertainty and imprecision. This book is based on a NATO Advanced Study Institute held in 1996 on soft computing and its applications. The distinguished contributors consider the principal constituents of soft computing, namely fuzzy logic, neurocomputing, genetic computing, and probabilistic reasoning, the relations between them, and their fusion in industrial applications. Two areas emphasized in the book are how to achieve a synergistic combination of the main constituents of soft computing and how the combination can be used to achieve a high Machine Intelligence Quotient.

Neural and Fuzzy Logic Control of Drives and Power Systems

Methods and Applications of Intelligent Control

Intelligent Control; Aspects of Fuzzy Logic and Neural Nets

Intelligent Control Systems with LabVIEW™

Recent Advances in Intelligent Control Systems

This book describes important techniques, developments, and applications of computational intelligence in system control. Chapters present: an introduction to the fundamentals of neural networks, fuzzy logic, and evolutionary computing a rigorous treatment of intelligent control industrial applications of intelligent control and soft computing, including transportation, petroleum, motor drive, industrial automation, and fish processing other knowledge-based techniques, including vehicle driving aid and air traffic management Intelligent Adaptive Control provides a state-of-the-art treatment of practical applications of computational intelligence in system control. The book cohesively covers introductory and advanced theory, design, implementation, and industrial use – serving as a singular resource for the theory and application of intelligent control, particularly employing fuzzy logic, neural networks, and evolutionary computing.

With increasing demands for high precision autonomous control over wide operating envelopes, conventional control engineering approaches are unable to adequately deal with system complexity, nonlinearities, spatial and temporal parameter variations, and with uncertainty. Intelligent Control or self-organising/learning control is a new emerging discipline that is designed to deal with problems. Rather than being model based, it is experiential based. Intelligent Control is the amalgam of the disciplines of Artificial Intelligence, Systems Theory and Operations Research. It uses most recent experiences or evidence to improve its performance through a variety of learning schemas, that for practical implementation must demonstrate rapid learning convergence, be temporally stable, be robust to parameter changes and internal and external disturbances. It is shown in this book that a wide class of fuzzy logic and neural net based learning algorithms satisfy these conditions. It is demonstrated that this class of intelligent controllers is based upon a fixed nonlinear mapping of the input (sensor) vector, followed by an output layer linear mapping with coefficients that are updated by various first order learning laws. Under these conditions self-organising fuzzy logic controllers and neural net controllers have common learning attributes. A theme example of the navigation and control of an autonomous guided vehicle is included throughout, together with a series of bench examples to demonstrate this new theory and its applicability. Contents:

An Introduction to Intelligent ControlIntroductory Fuzzy LogicFuzzy Logic Controller Structure and DesignThe Static Fuzzy Logic ControllerSelf-Organising Fuzzy Logic ControlIndirect Self-Organising Fuzzy Logic ControllersCase Studies of Direct Adaptive Fuzzy ControlNeural Network Approximation Capability for Control and ModellingThe B-Spline Neural Network and Fuzzy LogicThe Appendix: Mathematical Prerequisites Readership: Computer scientists, engineers and nonlinear scientists. Keywords:

This Encyclopedia of Control Systems, Robotics, and Automation is a component of the global Encyclopedia of Life Support Systems EOLSS, which is an integrated compendium of twenty one Encyclopedias. This 22-volume set contains 240 chapters, each of size 5000-30000 words, with perspectives, applications and extensive illustrations. It is the only publication of its kind carrying state-of-the-art knowledge in the fields of Control Systems, Robotics, and Automation and is aimed, by virtue of the several applications, at the following five major target audiences: University and College Students, Educators, Professional Practitioners, Research Personnel and Policy Analysts, Managers, and Decision Makers and NGOs.

With a strong emphasis on applications of intelligent control, this extremely accessible book covers the fundamentals, methodologies, architectures and algorithms of automatic control systems. The author summarizes several current concepts to improve industrial control systems, combining classical control techniques of dynamic modeling and control with new approaches discussed in the text. Addresses such intelligent systems as neural networks, fuzzy logic, ruled based, and genetic algorithms. Demonstrates how to develop, design and use intelligent systems to solve sophisticated industrial control problems. Includes numerous worked application examples.

Theory and Applications

Intelligent Control of Robotic Systems

Fuzzy Logic

Safety, Reliability and Applications of Emerging Intelligent Control Technologies

Intelligent Control Based on Fuzzy Logic and Constraint Processing

As robotic systems make their way into standard practice, they have opened the door to a wide spectrum of complex applications. Such applications usually demand that the robots be highly intelligent. Future robots are likely to have greater sensory capabilities, more intelligence, higher levels of manual dexterity, and adequate mobility, compared to humans. In order to ensure high-quality control and performance in robotics, new intelligent control techniques must be developed, which are capable of coping with task complexity, multi-objective decision making, large volumes of perception data and substantial amounts of heuristic information. Hence, the pursuit of intelligent autonomous robotic systems has been a topic of much fascinating research in recent years. On the other hand, as emerging technologies, Soft Computing paradigms consisting of complementary elements of Fuzzy Logic, Neural Computing and Evolutionary Computation are viewed as the most promising methods towards intelligent robotic systems. Due to their strong learning and cognitive ability and good tolerance of uncertainty and imprecision, Soft Computing techniques have found wide application in the area of intelligent control of robotic systems.

Introduction; Fuzzy control: the basics; Case studies in design and implementation; nonlinear analysis; Fuzzy identification and estimation; Adaptive fuzzy control; Fuzzy supervisory control. Perspectives on fuzzy control.

Providing equal emphasis on theoretical foundations and practical issues, this book features fuzzy logic concepts and techniques in intelligent systems, control, and information technology. Uses Fuzzy Logic Toolbox MATLAB to demonstrate exemplar applications and to develop hands-on exercises.

Trying to meet the requirements in the field, present book treats different fuzzy control architectures both in terms of the theoretical design and in terms of comparative validation studies in various applications, numerically simulated or experimentally developed. Through the subject matter and through the inter and multidisciplinary content, this book is addressed mainly to the researchers, doctoral students and students interested in developing new applications of intelligent control, but also to the people who want to become familiar with the control concepts based on fuzzy techniques. Bibliographic resources used to perform the work includes books and articles of present interest in the field, published in prestigious journals and publishing houses, and websites dedicated to various applications of fuzzy control. Its structure and the presented studies include the book in the category of those who make a direct connection between theoretical developments and practical applications, thereby constituting a real support for the specialists in artificial intelligence, modelling and control fields.

Fuzzy Logic Applications

Fuzzy and Intelligent Control Systems

Fuzzy Reasoning in Information, Decision and Control Systems

Aspects of Fuzzy Logic and Neural Nets

Intelligent Control Based on Fuzzy Logic and Neural Network Theory

The emergence of fuzzy logic and its applications has dramatically changed the face of industrial control engineering. Over the last two decades, fuzzy logic has allowed control engineers to meet and overcome the challenges of developing effective controllers for increasingly complex systems with poorly defined dynamics. Today's engineers need a working knowledge of the principles and techniques of fuzzy logic-Intelligent Control provides it. The author first introduces the traditional control techniques and contrasts them with intelligent control. He then presents several methods of representing and processing knowledge and introduces fuzzy logic as one such method. He highlights the advantages of fuzzy logic over other techniques, indicates its limitations, and describes in detail a hierarchical control structure appropriate for use in intelligent control systems. He introduces a variety of applications, most in the areas of robotics and mechatronics but with others including air conditioning and process/production control. One appendix provides discussion of some advanced analytical concepts of fuzzy logic, another describes a commercially available software system for developing fuzzy logic application. Intelligent Control is filled with worked examples, exercises, problems, and references. No prior knowledge of the subject nor advanced mathematics are needed to comprehend much of the book, making it well-suited as a senior undergraduate or first-year graduate text and a convenient reference tool for practicing professionals.

With increasing demands for high precision autonomous control over wide operating envelopes, conventional control engineering approaches are unable to adequately deal with system complexity, nonlinearities, spatial and temporal parameter variations, and with uncertainty. Intelligent Control or self-organising/learning control is a new emerging discipline that is designed to deal with problems. Rather than being model based, it is experiential based. Intelligent Control is the amalgam of the disciplines of Artificial Intelligence, Systems Theory and Operations Research. It uses most recent experiences or evidence to improve its performance through a variety of learning schemas, that for practical implementation must demonstrate rapid learning convergence, be temporally stable, be robust to parameter changes and internal and external disturbances. It is shown in this book that a wide class of fuzzy logic and neural net based learning algorithms satisfy these conditions. It is demonstrated that this class of intelligent controllers is based upon a fixed nonlinear mapping of the input (sensor) vector, followed by an output layer linear mapping with coefficients that are updated by various first order learning laws. Under these conditions self-organising fuzzy logic controllers and neural net controllers have common learning attributes.A theme example of the navigation and control of an autonomous guided vehicle is included throughout, together with a series of bench examples to demonstrate this new theory and its applicability.

Fuzzy Control of Industrial Systems: Theory and Applications presents the basic theoretical framework of crisp and fuzzy set theory, relating these concepts to control engineering based on the analogy between the Laplace transfer function of linear systems and the fuzzy relation of a nonlinear fuzzy system. Included are generic aspects of fuzzy systems with an emphasis on the many degrees of freedom and its practical design implications, modeling and systems identification techniques based on fuzzy rules, parametrized rules and relational equations, and the principles of adaptive fuzzy and neurofuzzy systems. Practical design aspects of fuzzy controllers are covered by the detailed treatment of fuzzy and neurofuzzy software design tools with an emphasis on iterative fuzzy tuning, while novel stability limit testing methods and the definition and practical examples of the new concept of collaborative control systems are also given. In addition, case studies of successful applications in industrial automation, process control, electric power technology, electric traction, traffic engineering, wastewater treatment, manufacturing, mineral processing and automotive engineering are also presented, in order to assist industrial control systems engineers in recognizing situations when fuzzy and neurofuzzy would offer certain advantages over traditional methods, particularly in controlling highly nonlinear and time-variant plants and processes.

This handbook shows the reader how to develop neural networks and apply them to various engineering control problems. Based on a workshop on aerospace applications, this tutorial covers integration of neural networks with existing control architectures as well as new neurocontrol architectures in nonlinear control.

Intelligent Control in Drying

Neural, Fuzzy, and Adaptive Approaches

Intelligence, Control, and Information

Fuzzy Logic and Intelligent Systems

#### Type-2 Fuzzy Logic in Intelligent Control Applications

This book offers a comprehensive introduction to intelligent control system design, using MATLAB simulation to verify typical intelligent controller designs. It also uses real-world case studies that present the results of intelligent controller implementations to illustrate the successful application of the theory. Addressing the need for systematic design approaches to intelligent control system design using neural network and fuzzy-based techniques, the book introduces the concrete design method and MATLAB simulation of intelligent control strategies; offers a catalog of implementable intelligent control design methods for engineering applications; provides advanced intelligent controller design methods and their stability analysis methods; and presents a sample simulation and Matlab program for each intelligent control algorithm. The main topics addressed are expert control, fuzzy logic control, adaptive fuzzy control, neural network control, adaptive neural control and intelligent optimization algorithms, providing several engineering application examples for each method.

Intelligent Control with LabVIEWTM is a fresh and pragmatic approach to the understanding of a subject often clouded by too much mathematical theory. It exploits the full suite of tools provided by LabVIEWTM, showing the student how to design, develop, analyze, and visualize intelligent control algorithms quickly and simply. Block diagrams are used to follow the progress of an algorithm through the design process and allow seamless integration with hardware systems for rapid deployment in laboratory experiments. This text delivers a thorough grounding in the main tools of intelligent control: fuzzy logic systems; artificial neural networks; neuro-fuzzy systems; evolutionary methods; and predictive methods. Learning and teaching are facilitated by: extensive use of worked examples; end of chapter problems with separate solutions; and provision of intelligent control tools for LabVIEWTM.

Intelligent Control considers non-traditional modelling and control approaches to nonlinear systems. Fuzzy logic, neural networks and evolutionary computing techniques are the main tools used. The book presents a modular switching fuzzy logic controller where a PD-type fuzzy controller is executed first followed by a PI-type fuzzy controller thus improving the performance of the controller compared with a PID-type fuzzy controller. The advantage of the switching-type fuzzy controller is that it uses one rule-base thus minimises the rule-base during execution. A single rule-base is developed by merging the membership functions for change of error of the PD-type controller and sum of error of the PI-type controller. Membership functions are then optimized using evolutionary algorithms. Since the two fuzzy controllers were executed in series, necessary further tuning of the differential and integral scaling factors of the controller is then performed. Neural-network-based tuning for the scaling parameters of the fuzzy controller is then described and finally an evolutionary algorithm is applied to the neurally-tuned-fuzzy controller in which the sigmoidal function shape of the neural network is determined. The important issue of stability is addressed and the text demonstrates empirically that the developed controller was stable within the operating range. The text concludes with ideas for future research to show the reader the potential for further study in this area. Intelligent Control will be of interest to researchers from engineering and computer science backgrounds working in the intelligent and adaptive control.

Despite the available general literature in intelligent control, there is a definite lack of knowledge and know-how in practical applications of intelligent control in drying. This book fills that gap. Intelligent Control in Drying serves as an innovative and practical guide for researchers and professionals in the field of drying technologies, providing an overview of control principles and systems used in drying operations, from classical to model-based to adaptive and optimal control. At the same time, it lays out approaches to synthesis of control systems, based on the objectives and control strategies, reflecting complexity of drying process and material under drying. This essential reference covers both fundamental and practical aspects of intelligent control, sensor fusion and dynamic optimization with respect to drying.

Industrial Intelligent Control  
Advances In Intelligent Control  
An Introduction with Examples  
Fundamentals and Applications

Computational Intelligence: Soft Computing and Fuzzy-Neuro Integration with Applications

***\*Introduces cutting-edge control systems to a wide readership of engineers and students \*The first book on neuro-fuzzy control systems to take a practical, applications-based approach, backed up with worked examples and case studies \*Learn to use VHDL in real-world applications***  
***Introducing cutting edge control systems through real-world applications Neural networks and fuzzy logic based systems offer a modern control solution to AC machines used in variable speed drives, enabling industry to save costs and increase efficiency by replacing expensive and high-maintenance DC motor systems. The use of fast micros has revolutionised the field with sensorless vector control and direct torque control. This book reflects recent research findings and acts as a useful guide to the new generation of control systems for a wide readership of advanced undergraduate and graduate students, as well as practising engineers. The authors guide readers quickly and concisely through the complex topics of neural networks, fuzzy logic, mathematical modelling of electrical machines, power systems control and VHDL design. Unlike the academic monographs that have previously been published on each of these subjects, this book combines them and is based round case studies of systems analysis, control strategies, design, simulation and implementation. The result is a guide to applied control systems design that will appeal equally to students and professional design engineers. The book can also be used as a unique VHDL design aid, based on real-world power engineering applications.***

***Soft computing, as a collection of techniques exploiting approximation and tolerance for imprecision and uncertainty in traditionally intractable problems, has become very effective and popular especially because of the synergy derived from its components. The integration of constituent technologies provides complementary methods that allow developing flexible computing tools and solving complex problems. A wide area of natural applications of soft computing techniques consists of the control of dynamic systems, including robots. Loosely speaking, control can be understood as driving a process to attain a desired goal. Intelligent control can be seen as an extension of this concept, to include autonomous human-like interactions of a machine with the environment. Intelligent robots can be characterized by the ability to operate in an uncertain, changing environment with the help of appropriate sensing. They have the power to autonomously plan and execute motion sequences to achieve a goal specified by a human user without detailed instructions. In this volume leading specialists address various theoretical and practical aspects in soft computing, intelligent robotics and control. The problems discussed are taken from fuzzy systems, neural networks, interactive evolutionary computation, intelligent mobile robotics, and intelligent control of linear and nonlinear dynamic systems.***

***We describe in this book, hybrid intelligent systems based mainly on type-2 fuzzy logic for intelligent control. Hybrid intelligent systems combine several intelligent computing paradigms, including fuzzy logic, and bio-inspired optimization algorithms, which can be used to produce powerful automatic control systems. The book is organized in three main parts, which contain a group of chapters around a similar subject. The first part consists of chapters with the main theme of theory and design algorithms, which are basically chapters that propose new models and concepts, which can be the basis for achieving intelligent control with interval type-2 fuzzy logic. The second part of the book is comprised of chapters with the main theme of evolutionary optimization of type-2 fuzzy systems in intelligent control with the aim of designing optimal type-2 fuzzy controllers for complex control problems in diverse areas of application, including mobile robotics, aircraft dynamics systems and hardware implementations. The third part of the book is formed with chapters dealing with the theme of bio-inspired optimization of type-2 fuzzy systems in intelligent control, which includes the application of particle swarm intelligence and ant colony optimization algorithms for obtaining optimal type-2 fuzzy controllers.***

***"Recent Advances in Intelligent Control Systems" gathers contributions from workers around the world and presents them in four categories according to the style of control employed: fuzzy control; neural control; fuzzy neural control; and intelligent control. The contributions illustrate the interdisciplinary antecedents of intelligent control and contrast its results with those of more traditional control methods. A variety of design examples, drawn primarily from robotics and mechatronics but also representing process and production engineering, large civil structures, network flows, and others, provide instances of the application of computational intelligence for control. Presenting state-of-the-art research, this collection will be of benefit to researchers in automatic control, automation, computer science (especially artificial intelligence) and mechatronics while graduate students and practicing control engineers working with intelligent systems will find it a good source of study material.***

#### Fuzzy Control of Industrial Systems

#### Intelligent Control Design and MATLAB Simulation

#### Power Electronic Systems

#### Intelligent Control Systems

#### Fuzzy Controllers

*Increasingly, over the last few years, intelligent controllers have been incorporated into control systems. Presently, the numbers and types of intelligent controllers that contain variations of fuzzy logic, neural network, genetic algorithms or some other forms of knowledge based reasoning technology are dramatically rising. However, considering the stability of the system, when such controllers are included it is difficult to analyse and predict system behaviour under unexpected conditions. Leading researchers and industrial practitioners were able to discuss and evaluate current development and future research directions at the first IFAC International Workshop on safety, reliability and applications on emerging intelligent control technology. This publication contains the papers, covering a wide range of topics, presented at the workshop.*

*Intelligent control is a rapidly developing, complex and challenging field with great practical importance and potential. Because of the rapidly developing and interdisciplinary nature of the subject, there are only a few edited volumes consisting of research papers on intelligent control systems but little is known and published about the fundamentals and the general know-how in designing, implementing and operating intelligent control systems. Intelligent control system emerged from artificial intelligence and computer controlled systems as an interdisciplinary field. Therefore the book summarizes the fundamentals of knowledge representation, reasoning, expert systems and real-time control systems and then discusses the design, implementation verification and operation of real-time expert systems using G2 as an example. Special tools and techniques applied in intelligent control are also described including qualitative modelling, Petri nets and fuzzy controllers. The material is illustrated with simple examples taken from the field of intelligent process control.*

*Introducion; Methology of knowledge representation; General inference principles; Hierarchical control systems; Expert control systems; Fuzzy control systems; Neurocontrol systems; Learning control systems; Intelligente control systems in application; Prospectives of intelligente control; References; Bibliography; Subject index.*

*In recent years, intelligent control has emerged as one of the most active and fruitful areas of research and development. Until now, however, there has been no comprehensive text that explores the subject with focus on the design and analysis of biological and industrial applications. Intelligent Control Systems Using Soft Computing Methodologies does all that and more. Beginning with an overview of intelligent control methodologies, the contributors present the fundamentals of neural networks, supervised and unsupervised learning, and recurrent networks. They address various implementation issues, then explore design and verification of neural networks for a variety of applications, including medicine, biology, digital signal processing, object recognition, computer networking, desalination technology, and oil refinery and chemical processes. The focus then shifts to fuzzy logic, with a review of the fundamental and theoretical aspects, discussion of implementation issues, and examples of applications, including control of autonomous underwater vehicles, navigation of space vehicles, image processing, robotics, and energy management systems. The book concludes with the integration of genetic algorithms into the paradigm of soft computing methodologies, including several more industrial examples, implementation issues, and open problems and open problems related to intelligent control technology. Suitable as a textbook or a reference, Intelligent Control Systems explores recent advances in the field from both the theoretical and the practical viewpoints. It also integrates intelligent control design methodologies to give designers a set of flexible, robust controllers and provide students with a tool for solving the examples and exercises within the book.*

Industrial Applications

Fuzzy Control

Handbook of Intelligent Control

Aspects of Soft Computing, Intelligent Robotics and Control

Intelligent Control Systems Using Soft Computing Methodologies