

Fanuc Roboguide Software

This text may be used to teach the fundamental concepts and skills of computer programming. Using a language similar to PASCAL, it introduces the simulator Karel the Robot and teaches readers to develop good programming habits as they design programs that instruct Karel to perform certain tasks.

Grippers in Motion provides a comprehensive, practice-oriented guide to the fascinating details of automation processes involving gripping and manipulation. This intriguing and colorful book leads the reader from the history of automation and robotics to the fundamentals of the gripping process as well as the interaction of the gripping process with the fundamental workpieces. Boundary conditions and initial situation of the gripping process are defined, and how subsequent motion follows gripping is shown. The implementation of these motion processes, from simple linear motions to the kinematics of multiple axes, is illustrated in a practical way. This practical introduction motivates students and even professionals to learn more about the world of robotic grippers. Grippers in Motion includes a spectrum of real-world applications demonstrating the possibilities and varieties of automation in practice.

In two editions spanning more than a decade, The Electrical Engineering Handbook stands as the definitive reference to the multidisciplinary field of electrical engineering. Our knowledge continues to grow, and so does the Handbook. For the third edition, it has grown into a set of six books carefully focused on specialized areas or fields of study. Each one represents a concise yet definitive collection of key concepts, models, and equations in its respective domain, thoughtfully gathered for convenient access. Combined, they constitute the most comprehensive, authoritative resource available. Circuits, Signals, and Speech and Image Processing presents all of the basic information related to electric circuits and components, analysis of circuits, and the use of the Laplace transform, as well as signal, speech, and image processing using filters and algorithms. It also examines emerging areas such as text to speech synthesis, real-time processing, and embedded signal processing. Electronics, Power Electronics, Optoelectronics, Microwaves, Electromagnetics, and Radar delves into the fields of electronics, integrated circuits, power electronics, optoelectronics, electromagnetics, light waves, and radar, supplying all of the basic information required for a deep understanding of each area. It also devotes a section to electrical effects and devices and explores the emerging fields of micro lithography and power electronics. Sensors, Nanoscience, Biomedical Engineering, and Instruments provides thorough coverage of sensors, materials and nanoscience, instruments and measurements, and biomedical systems and devices, including all of the basic information required to thoroughly understand each area. It explores the emerging fields of sensors, nanotechnologies, and biological effects. Broadcasting and Optical Communication Technology explores communications, information theory, and devices, covering all of the basic information needed for a thorough understanding of these areas. It also examines the emerging areas of adaptive estimation and optical communication. Computers, Software Engineering, and Digital Devices examines digital and logical devices, displays, testing, software, and computers, presenting the fundamental concepts needed to ensure a thorough understanding of each field. It treats the emerging fields of programmable logic, hardware description languages, and parallel computing in detail. Systems, Controls, Embedded Systems, Energy, and Machines explores in detail the fields of energy devices, machines, and systems as well as control systems. It provides all of the fundamental concepts needed for thorough, in-depth understanding of each area and devotes special attention to the emerging area of embedded systems. Encompassing the work of the world's foremost experts in their respective specialties, The Electrical Engineering Handbook, Third Edition remains the most convenient, reliable source of information available. This edition features the latest developments, the broadest scope of coverage, and new material on nanotechnologies, fuel cells, embedded systems, and biometrics. The engineering community has relied on the Handbook for more than twelve years, and it will continue to be a platform to launch the next wave of advancements. The Handbook's latest incarnation features a protective slipcase, which helps you stay organized without overwhelming your bookshelf. It is an attractive addition to any collection, and will help keep each volume of the Handbook as fresh as your latest research.

This book of proceedings is the synthesis of all the papers, including keywords presented during the 20th CIRP Design conference. The book is structured with respect to several topics, in fact the main topics that serve at structuring the program. For each of them, high quality papers are provided. The main topic of the conference was Global Product Development. This includes technical, organizational, informational, theoretical, environmental, performance evaluation, knowledge management, and collaborative aspects. Special sessions were related to innovation, in particular extraction of knowledge from patents.

Thermal Spray Coatings

14th International Conference, ICIRA 2021, Yantai, China, October 22–25, 2021, Proceedings, Part III

Karel the Robot

Proceedings of the 15th IFToMM World Congress on Mechanism and Machine Science

First International Conference, OL2A 2021, Bragaça, Portugal, July 19-21, 2021, Revised Selected Papers

Types, Designs, Manufacture and Applications

ROBOT 2017: Third Iberian Robotics Conference

The primary aim of this volume is to provide researchers and engineers from both academic and industry with up-to-date coverage of new results in the field of robotic welding, intelligent systems and automation. The book is mainly based on papers selected from the 2014 International Conference on Robotic Welding, Intelligence and Automation (RWIA ' 2014), held Oct. 25-27, 2014, at Shanghai, China. The articles show that the intelligentized welding manufacturing (IWM) is becoming an inevitable trend with the intelligentized robotic welding as the key technology. The volume is divided into four logical parts: Intelligent Techniques for Robotic Welding, Sensing of Arc Welding Processing, Modeling and Intelligent Control of Welding Processing, as well as Intelligent Control and its Applications in Engineering.

Parallel structures are more effective than serial ones for industrial automation applications that require high precision and stiffness, or a high load capacity relative to robot weight. Although many industrial applications have adopted parallel structures for their design, few textbooks introduce the analysis of such robots in terms of dynamics and control. Filling this gap, Parallel Robots: Mechanics and Control presents a systematic approach to analyze the kinematics, dynamics, and control of parallel robots. It brings together analysis and design tools for engineers and researchers who want to design and implement parallel structures in serial, covers Kinematics, Dynamics, and Control in One Volume! The book begins with the representation of motion of robots and the kinematic analysis of parallel manipulators. Moving beyond static positioning, it then examines a systematic approach to performing Jacobian analysis. A special feature of the book is its detailed coverage of the dynamics and control of parallel manipulators. The text examines dynamic analysis using the Newton-Euler method, the principle of virtual work, and the Lagrange formulations. Finally, the book elaborates on the control of parallel robots, motion and force control. It introduces various model-free and model-based controllers and develops robust and adaptive control schemes. It also addresses redundancy resolution schemes in detail. Analysis and Design Tools to Help You Create Parallel Robots In each chapter, the author revisits the same case studies to show how the techniques may be applied. The case studies include a planar cable-driven parallel robot, part of a promising new generation of parallel structures that will allow for larger workspaces. The MATLAB code used for analysis and simulation is available online. Combining the analysis of kinematics and dynamics with methods of designing controllers, this text offers a holistic introduction for anyone interested in designing and implementing parallel robots.

Biomechatronics is rapidly becoming one of the most influential and innovative research directions defining the 21st century. Biomechatronics will provide a complete and up-to-date account of this advanced subject at the university textbook level. Each chapter in this book will be co-authored by top industry experts in the corresponding subfield, and will be led by Professor Marko B. Popovic, researcher and educator at the forefront of advances in the biomechatronics field. Beginning with an introduction to the field and its historical background, this book will delve into the most groundbreaking and recent developments in biomechatronics, such as artificial organs and tissues, prosthetic limbs, orthotic systems, wearable systems for physical augmentation, physical therapy and rehabilitation, robotic surgery, and natural and synthetic sensors. The only biomechatronics textbook written especially for students at a university level Ideal for undergraduate and graduate students and researchers in the biomechatronics, biomechanics, robotics, and biomedical engineering fields Provides an overview of state-of-the-art science and technology of modern day biomechatronics, introduced by the leading experts in this fascinating field

This book highlights recent findings in industrial, manufacturing and mechanical engineering, and provides an overview of the state of the art in these fields, mainly in Russia and Eastern Europe. A broad range of topics and issues in modern engineering are discussed, including the dynamics of machines and working processes, friction, wear and lubrication in machines, surface transport and technological machines, manufacturing engineering of industrial facilities, materials engineering, metallurgy, control systems and their industrial applications, industrial mechatronics, automation and robotics.

The book gathers selected papers presented at the 6th International Conference on Industrial Engineering (ICIE), held in Sochi, Russia in May 2020. The authors are experts in various fields of engineering, and all papers have been carefully reviewed. Given its scope, the book will be of interest to a wide readership, including mechanical and production engineers, lecturers in engineering disciplines, and engineering graduates.

Future Development of Thermal Spray Coatings

Collaborative Networks and Digital Transformation

Systems, Controls, Embedded Systems, Energy, and Machines

Mechatronics by Bond Graphs

ICT Systems and Sustainability

Handbuch Industrie 4.0: Recht, Technik, Gesellschaft

Advances in Mechanism and Machine Science

The handbook presents an overview of Industry 4.0 and offers solutions for important practical questions. The law and its current challenges regarding data assignment (who owns the data? / EU guidelines), data security, data protection (General Data Protection Regulation), cyberattacks, competition law (right to access vs. monopolistic, permissible and prohibited exchanges of information, possible collaborations) is the point of departure. In turn, the book explores peculiarities in specific areas of Industry 4.0 (Internet of Production, mechanical engineering, artificial intelligence, electromobility, autonomous driving, traffic, medical science, construction, energy industry, etc.). The book's closing section addresses general developments in management, the digital transformation of companies and the world of work, and ethical questions.

This book gathers the proceedings of the 15th IFToMM World Congress, which was held in Krakow, Poland, from June 30 to July 4, 2019. Having been organized every four years since 1965, the Congress represents the world's largest scientific event on mechanism and machine science (MMS). The contributions cover an extremely diverse range of topics, including biomechanical engineering, computational kinematics, design methodologies, dynamics of machinery, multibody dynamics, gearing and transmissions, history of MMS, linkage and mechanical controls, robotics and mechatronics, micro-mechanisms, reliability of machines and mechanisms, robot dynamics, standardization of terminology, sustainable energy systems, transportation machinery, tribology and vibration. Selected by means of a rigorous international peer-review process, they highlight numerous exciting advances and ideas that will spur novel research directions and foster new multidisciplinary collaborations.

The 4-volume set LNAI 13013 - 13016 constitutes the proceedings of the 14th International Conference on Intelligent Robotics and Applications, ICIRA 2021, which took place in Yantai, China, during October 22-25, 2021. The 299 papers included in these proceedings were carefully reviewed and selected from 386 submissions. They were organized in topical sections as follows: Robotics dexterous manipulation; sensors, actuators, and controllers for soft and hybrid robots; cable-driven parallel robot; human-centered wearable robotics; hybrid system modeling and human-machine interface; robot manipulation skills learning; micro_nano materials, devices, and systems for biomedical applications; actuating, sensing, control, and instrumentation for ultra-precision engineering; human-robot collaboration; robotic machining; medical robot; machine intelligence for human motion analytics; human-robot interaction for service robots; novel mechanisms, robots and applications; space robot and on-orbit service; neural learning enhanced motion planning and control for human robot interaction; medical engineering.

Collection of selected, peer reviewed papers from the 12th International Conference on Modern Technologies in Manufacturing (MTeM) October 14-16, 2015, Cluj-Napoca, Romania. The 59 papers are grouped as follows: Chapter 1: Processes of Metal Machining Chapter 2: Metal Forming Chapter 3: Processing of Plastics and Composite Materials Chapter 4: Additive Manufacturing and Non-traditional Technologies Chapter 5: Computer Aided Design and Manufacturing Chapter 6: Automation of Manufacturing Systems and Assembly Chapter 7: Manufacturing Engineering

Proceedings of the 6th International Conference on Industrial Engineering (ICIE 2020)

Industrial robots and cobots

Modern Robotics

Human Interface and the Management of Information. Visual Information and Knowledge Management

Robot Vision

Optimization, Learning Algorithms and Applications

Proceedings of the 20th CIRP Design Conference, Ecole Centrale de Nantes, Nantes, France, 19th-21st April 2010

This book constitutes the proceedings of the International Conference on Research and Education in Robotics, EUROBOT 2011, held in Prague, Czech Republic, in June 2011. The 28 revised full papers presented were carefully reviewed and selected from numerous submissions. The papers present current basic research such as robot control and behaviour, applications of autonomous intelligent robots, and perception, processing and action; as well as educationally oriented papers addressing issues like robotics at school and at university, practical educational robotics activities, practices in educational robot design, and future technical activities.

This book provides the latest information about the research being conducted and established solutions available in the field of thermal spray coatings for various engineering applications. The readers of this book will be mainly the graduates, engineers and researchers who are pursuing their carrier in the field of thermal spraying. This book will cover the studies and research works of reputed scientists and engineers who have developed thermal spray coatings for thermal protection, bio-implants, renal energy, wear and corrosion in hydraulic turbines and jet engines, hydrophobic surfaces etc. Hence, the book serves as a valuable resource of latest advancement in thermal spray technology and consolidated references for aspirants and professionals of surface engineering community. The book covers following topics for different industrial applications: Introduction: Historical developments, Science and Engineering aspects of thermal spray coating technology and different thermal spray coatings techniques and its comparison with other fabrication processes. Recent advancements and applications of thermal spray coatings for additive manufacturing. High-temperature corrosion and erosion resistant coatings and thermal barrier coatings for power plants, automotive sector, and jet engines. Erosion and corrosion-resistant coatings for hydro-power plants, offshore, chemical and oil industries. Bio-coatings for human body implants. Thermal spray coating for super-hydrophobic surface. 3. Case study of boiler tubes failure and prevention by thermal spray coatings.

Over the past five years robot vision has emerged as a subject area with its own identity. A text based on the proceedings of the Symposium on Computer Vision and Sensor-based Robots held at the General Motors Research Laboratories, Warren, Michigan in July 30 to July 4, 1979. This book, edited by George G. Dodd and Lothar Rosso!, probably represented the first identifiable book covering some aspects of robot vision. The subject of robot vision and sensory controls (RoViSc) occupied an entire international conference held in the Hilton Hotel in Stratford, England in May 1981. This was followed by a second RoViSc! held in Stuttgart, Germany in November 1982. The large attendance at the Stratford conference and the obvious interest in the subject of robot vision at international robot meetings, provides the stimulus for this current collection of papers. Users and researchers entering the field of robot vision for the first time will encounter a bewildering array of publications on all aspects of computer vision of which robot vision forms a part. It is the grey area dividing the different aspects of computer vision which is not easy to identify. Even those involved in research sometimes find difficulty in separating the essential differences between computer vision and vision for robot applications. Both of these are to some extent collections of patterns recognition with the underlying philosophy of each defining the techniques used.

Das Handbuch bietet einen Gesamtüberblick über Industrie 4.0 und gibt zugleich Lösungen für wichtige praktische Fragen. Ausgangspunkt ist dabei das Recht mit seinen aktuellen Herausforderungen Zuordnung der Daten (wem gehören sie? Vorgaben der EU?), Datensicherheit, Datenschutz (Europäische Datenschutzgrundverordnung), Cyberangriffe, Wettbewerbsrecht (Zugangsansprüche gegen Monopolisten, zulässiger und verbotener Informationsaustausch, mögliche Kooperationen). Sodann werden Einzelbereiche von Industrie 4.0 (Internet of Production, Maschinenbau, künstliche Intelligenz, Elektromobilität, autonomes Fahren, Verkehr, Medizin, Bauwesen, Energiewirtschaft etc.) in ihren Besonderheiten beleuchtet. Allgemeine Entwicklungen aus dem Management, der digitalen Transformation der Unternehmen und der Arbeitswelt sowie ethische Fragen schließen sich an.

Volume II

Modern Technologies in Manufacturing

Modern Graphics Communication

Redesigning the Learning Experience

Thematic Area, HMI 2019, Held as Part of the 21st HCI International Conference, HCII 2019, Orlando, FL, USA, July 26–31, 2019, Proceedings, Part I

Software for Industrial Automation

Adaptierbares aufgabenorientiertes Programmiersystem für Montagesysteme

A modern and unified treatment of the mechanics, planning, and control of robots, suitable for a first course in robotics.

ICT Systems and SustainabilityProceedings of ICT4SD 2021, Volume 1Springer Nature

This is a clear, comprehensive, full-color introduction and reference for students and professionals who are creating engineering drawings and graphics with CAD software or by hand. It provides excellent technical detail and motivating real-world examples, illuminating theory with a colorful, highly-visual format complemented with concise text. Designed for busy, visually-oriented learners, this guide expands on well-tested material, fully updated for the latest ASME standards, materials, industries and production processes. Its up-to-date examples range from mechanical, plastic, and sheet metal drawings to modern techniques for civil engineering, architecture, and rapid prototyping. Throughout, clear, easy, step-by-step descriptions teach essential sketching and visualization techniques, including the use of 3D and 2D CAD. All color visuals are tightly integrated with text to promote rapid mastery. Colorful models and animations on a companion website bring the material to life, and hands-on projects and tear-out worksheets make this guide ideal both for learning and for ongoing reference.

In two editions spanning more than a decade, The Electrical Engineering Handbook stands as the definitive reference to the multidisciplinary field of electrical engineering. Our knowledge continues to grow, and so does the Handbook. For the third edition, it has expanded into a set of six books carefully focused on a specialized area or field of study. Each book represents a concise yet definitive collection of key concepts, models, and equations in its respective domain, thoughtfully gathered for convenient access. Systems, Controls, Embedded Systems, Energy, and Machines explores in detail the fields of energy devices, machines, and systems as well as control systems. It provides all of the fundamental concepts needed for thorough, in-depth understanding of each area and devotes special attention to the emerging area of embedded systems. Each article includes defining terms, references, and sources of further information. Encompassing the work of the world's foremost experts in their respective specialties, Systems, Controls, Embedded Systems, Energy, and Machines features the latest developments, the broadest scope of coverage, and new material on human-computer interaction.

Official Gazette of the United States Patent and Trademark Office

An Object-Oriented Approach to Modelling and Simulation

Deep Learning for Robot Perception and Cognition

International Conference, Prague, Czech Republic, June 15–17, 2011. Proceedings

Law, Technology, Society

Proceedings of ICT4SD 2021, Volume 1

Robotic automation has become ubiquitous in the modern manufacturing landscape, spanning an overwhelming range of processes and applications-- from small scale force-controlled grinding operations for orthopedic joints to large scale composite manufacturing of aircraft fuselages. Smart factories, seamlessly linked via industrial networks and sensing, have revolutionized mass production, allowing for intelligent, adaptive manufacturing processes across a broad spectrum of industries. Against this background, an emerging group of researchers, designers, and fabricators have begun to apply robotic technology in the pursuit of architecture, art, and design, implementing them in a range of processes and scales. Coupled with computational design tools the technology is no longer relegated to the repetitive production of the assembly line, and is instead being employed for the mass-customization of non-standard components. This radical shift in protocol has been enabled by the development of new design to production workflows and the recognition of robotic manipulators as "multi-functional" fabrication platforms, capable of being reconfigured to suit the specific needs of a process. The emerging discourse surrounding robotic fabrication seeks to question the existing norms of manufacturing and has far reaching implications for the future of how architects, artists, and designers engage with materialization processes. This book presents the proceedings of RobiArch2018, the second international conference on robotic fabrication in architecture, art, and design. It includes a Foreword by Sigrid Brell-Cokcan and Johannes Braumann, Association for Robots in Architecture. The work contained traverses a wide range of contemporary topics, from methodologies for incorporating dynamic material feedback into existing fabrication processes, to novel interfaces for robotic programming, to novel fabrication techniques.

This book constitutes the refereed proceedings of the 20th IFIP WG 5.5 Working Conference on Virtual Enterprises, PRO-VE 2019, held in Turin, Italy, in September 2019. The 56 revised full papers were carefully reviewed and selected from 141 submissions. They provide a comprehensive overview of major challenges and recent advances in various domains related to the digital transformation and collaborative networks and their applications with a strong focus on the following areas related to the main theme of the conference: collaborative models, platforms and systems for digital evolution; manufacturing ecosystem and collaboration in Industry 4.0; big data analytics and intelligence; risk, performance, and uncertainty in collaborative networked systems; semantic data/service discovery, retrieval, and composition in a collaborative networked world; trust and sustainability analysis in collaborative networks; value creation and social impact of collaborative networks on the digital revolution; technology development platforms supporting collaborative systems; collective intelligence and collaboration in advance/emerging applications; and collaborative manufacturing and factories of the future, e-health and care, food and agribusiness, and crisis/disaster management.

These volumes of "Advances in Intelligent Systems and Computing" highlight papers presented at the "Third Iberian Robotics Conference (ROBOT 2017)". Held from 22 to 24 November 2017 in Seville, Spain, the conference is a part of a series of conferences co-organized by SEIDROB (Spanish Society for Research and Development in Robotics) and SPR (Portuguese Society for Robotics). The conference is focused on Robotics scientific and technological activities in the Iberian Peninsula, although open to research and delegates from other countries. Thus, it has more than 500 authors from 21 countries. The volumes present scientific advances but also robotic industrial applications, looking to promote new collaborations between industry and academia.

This book discusses approaches in advancing STEM education with the use of robotics, innovative methods in integrating robotics in school subjects, engaging and stimulating students with robotics in classroom-based and out-of-school activities, and new ways of using robotics as an educational tool to provide diverse learning experiences. It addresses issues and challenges in generating enthusiasm among students and revamping curricula to provide application focused and hands-on approaches in learning. The book also provides effective strategies and emerging trends in using robotics, designing learning activities and how robotics impacts the students' interests and achievements in STEM related subjects. The frontiers of education are progressing very rapidly. This volume brought together a collection of projects and ideas which help us keep track of where the frontiers are moving. This book ticks lots of contemporary boxes: STEM, robotics, coding, and computational thinking among them. Most educators interested in the STEM phenomena will find many ideas in this book which challenge, provide evidence and suggest solutions related to both pedagogy and content. Regular reference to 21st Century skills, achieved through active collaborative learning in authentic contexts, ensures the enduring usefulness of this volume. John Williams Professor of Education and Director of the STEM Education Research Group Curtin University, Perth, Australia

A Gentle Introduction to the Art of Programming

Trademarks

Manufacturing Engineering

RWIA'2014

Grippers in Motion

The Electrical Engineering Handbook - Six Volume Set

A Work-piece Based Approach for Programming Cooperating Industrial Robots

Future Development of Thermal Spray Coatings discusses the latest developments and research trends in the thermal spray industry. The book presents a timely guide to new applications and techniques. After an introduction to thermal spray coatings by the editor, Part One covers new types and properties of thermal spray coatings. Chapters look at feedstock suspensions and solutions, the application of solution precursor spray techniques to obtain ceramic films and coatings, cold spray techniques and warm spray technology amongst others. Part Two of the book moves on to discuss new applications for thermal spray coatings such as the use of thermal spray coatings in environmental barrier coatings, thermal spray coatings in renewable energy applications and manufacturing engineering in thermal spray technologies by advanced robot systems and process kinematics. Timely guide on the current advancements and research trends in thermal spray technology Reviews different types of thermal spray coatings Presents a wide variety of applications for this emerging technology

This book presents a computer-aided approach to the design of mechatronic systems. Its subject is an integrated modeling and simulation in a visual computer environment. Since the first edition, the simulation software changed enormously, became more user-friendly and easier to use. Therefore, a second edition became necessary taking these improvements into account. The modeling is based on system top-down and bottom-up approach. The mathematical models are generated in a form of differential-algebraic equations and solved using numerical and symbolic algebra methods. The integrated approach developed is applied to mechanical, electrical and control systems, multibody dynamics, and continuous systems.

This book proposes new technologies and discusses future solutions for ICT design infrastructures, as reflected in high-quality papers presented at the 6th International Conference on ICT for Sustainable Development (ICT4SD 2021), held in Goa, India, on 5–6 August 2021. The book covers the topics such as big data and data mining, data fusion, IoT programming toolkits and frameworks, green communication systems and network, use of ICT in smart cities, sensor networks and embedded system, network and information security, wireless and optical networks, security, trust, and privacy, routing and control protocols, cognitive radio and networks, and natural language processing. Bringing together experts from different countries, the book explores a range of central issues from an international perspective.

This book discusses approaches in advancing STEM education with the use of robotics, innovative methods in integrating robotics in school subjects, engaging and stimulating students with robotics in classroom-based and out-of-school activities, and new ways of using robotics as an educational tool to provide diverse learning experiences. It addresses issues and challenges in generating enthusiasm among students and revamping curricula to provide application focused and hands-on approaches in learning. The book also provides effective strategies and emerging trends in using robotics, designing learning activities and how robotics impacts the students' interests and achievements in STEM related subjects. The frontiers of education are progressing very rapidly. This volume brought together a collection of projects and ideas which help us keep track of where the frontiers are moving. This book ticks lots of contemporary boxes: STEM, robotics, coding, and computational thinking among them. Most educators interested in the STEM phenomena will find many ideas in this book which challenge, provide evidence and suggest solutions related to both pedagogy and content. Regular reference to 21st Century skills, achieved through active collaborative learning in authentic contexts, ensures the enduring usefulness of this volume. John Williams Professor of Education and Director of the STEM Education Research Group Curtin University, Perth, Australia

Robotics in STEM Education

Research and Education in Robotics - EUROBOT 2011

20th IFIP WG 5.5 Working Conference on Virtual Enterprises, PRO-VE 2019, Turin, Italy, September 23–25, 2019, Proceedings

Intelligent Robotics and Applications

Mechanics and Control

Parallel Robots

Robotic Welding, Intelligence and Automation

This two-volume set LNCS 11569 and 11570 constitutes the refereed proceedings of the Thematic Area on Human Interface and the Management of Information, HMI 2019, held as part of HCI International 2019 in Orlando, FL, USA. HCI 2019 received a total of 5029 submissions, of which 1275 papers and 209 posters were accepted for publication after a careful reviewing process. The 91 papers presented in the two volumes were organized in topical sections named: Visual information; Data visualization and analytics; Information, cognition and learning; Information, empathy and persuasion; Knowledge management and sharing; Haptic and tactile interaction; Information in virtual and augmented reality; Machine learning and intelligent systems; Human motion and expression recognition and tracking; Medicine, healthcare and quality of life applications.

A major revision of the international bestseller on game programming/Graphics hardware has evolved enormously in the last decade. Hardware can now be directly controlled through techniques such as shader programming, which requires an entirely new thought process of a programmer. 3D Game Engine Design, Second Edition shows step-by-step how to make

This book constitutes selected and revised papers presented at the First International Conference on Optimization, Learning Algorithms and Applications, OL2A 2021, held in Bragaça, Portugal, in July 2021. Due to the COVID-19 pandemic the conference was held online. The 39 full papers and 13 short papers were thoroughly reviewed and selected from 134 submissions. They are organized in the topical sections on optimization theory; robotics; measurements with the internet of things; optimization in control systems design; deep learning; data visualization and virtual reality; health informatics; data analysis; trends in engineering education

In the modern world, highly repetitive and tiresome tasks are being delegated to machines. The demand for industrial robots is growing not only because of the need to improve production efficiency and the quality of the end products, but also due to rising employment costs and a shortage of skilled professionals. The industrial robot market is projected to grow by 16% year-on-year in the immediate future. The industry ’ s progressing automation is increasing the demand for specialists who can operate robots. If you would like to join this sought-after and well-paid professional group, it ’ s time to learn how to operate and program robots using modern methods. This book provides all the information you will need to enter the industry without spending money on training or looking for someone willing to introduce you to the world of robotics. You will learn about all aspects of programming and implementing robots in a company. The book consists of four parts: general introduction to robotics for non-technical people; part two describes industry robotisation; part three depicts the principles and methods of programming robots; the final part touches upon the safety of industrial robots and cobots. Are you a student of a technical faculty, or even a manager of a plant who would like to robotise production? If you are interested in this subject, you won ’ t find a better book!

ICMTMTE 2021

3D Game Engine Design

Robotic Fabrication in Architecture, Art and Design 2014

Manufacturing In The Era Of 4th Industrial Revolution: A World Scientific Reference (In 3 Volumes)

Everything you need to know about your future co-worker

Modern Trends in Manufacturing Technologies and Equipment

The Fascination of Automated Handling Tasks

The book presents the proceedings of the International Conference on Modern Trends in Manufacturing Technologies and Equipment (ICMTME 2021), held in September 2021 in Sevastopol, Russia. The conference participants came from Russia, Ukraine, Belarus, Kazakhstan, South Africa, Germany, USA, Bulgaria, Poland, China, Algeria, Mongolia, Uzbekistan, Armenia and Vietnam. The aim of the conference was to provide scientists and industrial researchers with the latest developments in manufacturing technologies, materials research, manufacturing equipment and tools, and to build up partnerships for future collaboration. Keywords: Welded Joints, Dry Building Mixtures, Tribological Properties of Sapphire, Direct Metal Deposition Modes, Production of Artificial Concrete, Wooden Structures, Rolls for Helical Rolling, Laser Treatments, Electromechanical Surfacing, Luminous Phosphate Coatings, Ventilated Brake Discs, Cutting Zone, Models for Wind Tunnels, Gas-Thermal Spraying, Water-Abrasive Cutting, Grinding Forces, CVD Coatings, Carbonate Concrete, Photocatalytic Activity of Tungsten Oxide, Maraging Steel, Corrosion of TiNi Alloy, 3D Printing, Production of Ultramarine, Injection Molding, Elastomeric Composites, Reinforcing Bars Inside Concrete Structures, Coatings for Cutting Tools, Hard Alloy Tools, Deformation of Elastic Polymer, Wearproof Composite Coatings. Rubber with Sensory Properties, Foamed Phosphate Glass for Oil Sorbents, Welded Trunk Pipelines, Biodegradable Extrusion Films, Asphalt Concrete, Mathematical Models, Electrically Conductive Materials, Belt Rotary Grinding of Aluminium Alloy Blanks.

Deep Learning for Robot Perception and Cognition introduces a broad range of topics and methods in deep learning for robot perception and cognition together with end-to-end methodologies. The book provides the conceptual and mathematical background needed for approaching a large number of robot perception and cognition tasks from an end-to-end learning point-of-view. The book is suitable for students, university and industry researchers and practitioners in Robotic Vision, Intelligent Control, Mechatronics, Deep Learning, Robotic Perception and Cognition tasks. Presents deep learning principles and methodologies Explains the principles of applying end-to-end learning in robotics applications Presents how to design and train deep learning models Shows how to apply deep learning in robot vision tasks such as object recognition, image classification, video analysis, and more Uses robotic simulation environments for training deep learning models Applies deep learning methods for different tasks ranging from planning and navigation to biosignal analysis

14th International Conference, ICIRA 2021, Yantai, China, October 22–25, 2021, Proceedings, Part IV

A Practical Approach to Real-Time Computer Graphics

Handbook Industry 4.0

Volume 2

Global Product Development

Biomechatronics