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"The Art of Agent-Oriented Modeling is an introduction to agent-oriented software development for students and for software developers who are interested in learning about new software engineering techniques."

--FOREWORD.

The tide toward the militarization of autonomous technologies has prompted critics to propose a pre-

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emptive ban on their development for fear that they may not adhere to international laws and, worse still, that no one will be responsible for their use. These criticisms, however, are rooted in pessimistic prognoses that misconstrue the potential of emerging technologies and international law's ability to regulate them. Accordingly, this thesis advances three arguments to dismantle these dystopian perspectives. First, a pre-emptive ban ignores the centuries-long distribution of violent tasks between humans and non-human actants. In the process, it seeks to revise current terminologies by shifting the focus on autonomy and lethality toward intelligence, violence, and systems. Second, the current international legal

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architecture is adequate to (a) ensure the responsible use of emerging autonomous weapons systems and (b) allocate human responsibility for their use. Critics often argue that it is impossible to preprogram all eventualities of warfare into a machine, but this perspective ignores advances in machine learning, that enable intelligent systems to teach themselves rules based on set parameters and algorithms. Third, critics misunderstand the networked nature of human violence, and consequently underestimate the elasticity of international law. To this end, this thesis borrows from evolutionary biology, psychology, and semiotics to explain the composition and constitution of networks of human

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violence. Ultimately, by viewing armed conflicts through the lenses of networks, this thesis argues that international law is capable of regulating human violence regardless of its conduit.

Everybody knows them. Smartphones that talk to us, wristwatches that record our health data, workflows that organize themselves automatically, cars, airplanes and drones that control themselves, traffic and energy systems with autonomous logistics or robots that explore distant planets are technical examples of a networked world of intelligent systems. Machine learning is dramatically changing our civilization. We rely more and more on efficient algorithms, because otherwise we will

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not be able to cope with the complexity of our civilizing infrastructure. But how secure are AI algorithms? This challenge is taken up in the 2nd edition: Complex neural networks are fed and trained with huge amounts of data (big data). The number of necessary parameters explodes exponentially. Nobody knows exactly what is going on in these "black boxes". In machine learning we need more explainability and accountability of causes and effects in order to be able to decide ethical and legal questions of responsibility (e.g. in autonomous driving or medicine)! Besides causal learning, we also analyze procedures of tests and verification to get certified AI-programs. Since its inception, AI research has been

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associated with great visions of the future of mankind. It is already a key technology that will decide the global competition of social systems. "Artificial Intelligence and Responsibility" is another central supplement to the 2nd edition: How should we secure our individual liberty rights in the AI world? This book is a plea for technology design: AI must prove itself as a service in society.

"This set of books represents a detailed compendium of authoritative, research-based entries that define the contemporary state of knowledge on technology"--Provided by publisher.

Modern Advances in Applied Intelligence

23rd International Conference on Industrial Engineering

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and Other Applications of Applied Intelligent Systems,
IEA/AIE 2010, Cordoba, Spain, June 1-4, 2010,
Proceedings, Part I

Autonomous Intelligent Systems: Multi-Agents and Data
Mining

Autonomous and Intelligent Systems

Introduction to AI Robotics, second edition

Convergence of Artificial Intelligence and the Internet of
Things

**This book constitutes the refereed
proceedings of the 12th Portuguese
Conference on Artificial Intelligence, EPIA
2005, held in Covilhã, Portugal in December**

2005 as nine integrated workshops. The 58 revised full papers presented were carefully reviewed and selected from a total of 167 submissions. In accordance with the nine constituting workshops, the papers are organized in topical sections on general artificial intelligence (GAIW 2005), affective computing (AC 2005), artificial life and evolutionary algorithms (ALEA 2005), building and applying ontologies for the semantic Web (BAOSW 2005), computational methods in bioinformatics (CMB 2005), extracting knowledge from

databases and warehouses (EKDB&W 2005), intelligent robotics (IROBOT 2005), multi-agent systems: theory and applications (MASTA 2005), and text mining and applications (TEMA 2005).

The second edition of a comprehensive introduction to all aspects of mobile robotics, from algorithms to mechanisms. Mobile robots range from the Mars Pathfinder mission's teleoperated Sojourner to the cleaning robots in the Paris Metro. This text offers students and other interested readers an introduction to the

fundamentals of mobile robotics, spanning the mechanical, motor, sensory, perceptual, and cognitive layers the field comprises. The text focuses on mobility itself, offering an overview of the mechanisms that allow a mobile robot to move through a real world environment to perform its tasks, including locomotion, sensing, localization, and motion planning. It synthesizes material from such fields as kinematics, control theory, signal analysis, computer vision, information theory, artificial intelligence, and probability theory. The book presents

the techniques and technology that enable mobility in a series of interacting modules. Each chapter treats a different aspect of mobility, as the book moves from low-level to high-level details. It covers all aspects of mobile robotics, including software and hardware design considerations, related technologies, and algorithmic techniques. This second edition has been revised and updated throughout, with 130 pages of new material on such topics as locomotion, perception, localization, and planning and navigation. Problem sets have been added

at the end of each chapter. Bringing together all aspects of mobile robotics into one volume, Introduction to Autonomous Mobile Robots can serve as a textbook or a working tool for beginning practitioners. Curriculum developed by Dr. Robert King, Colorado School of Mines, and Dr. James Conrad, University of North Carolina-Charlotte, to accompany the National Instruments LabVIEW Robotics Starter Kit, are available. Included are 13 (6 by Dr. King and 7 by Dr. Conrad) laboratory exercises for using the LabVIEW Robotics Starter Kit

to teach mobile robotics concepts.

Urban mobility is not only one of the pillars of modern economic systems, but also a key issue in the quest for equality of opportunity, once it can improve access to other services. Currently, however, there are a number of negative issues related to traffic, especially in mega-cities, such as economical issues (cost of opportunity caused by delays), environmental (externalities related to emissions of pollutants), and social (traffic accidents). Solutions to these issues are more and more

closely tied to information and communication technology. Indeed, a search in the technical literature (using the keyword "urban traffic" to filter out articles on data network traffic) retrieved the following number of articles (as of December 3, 2013): 9,443 (ACM Digital Library), 26,054 (Scopus), and 1,730,000 (Google Scholar). Moreover, articles listed in the ACM query relate to conferences as diverse as MobiCom, CHI, PADS, and AAMAS. This means that there is a big and diverse community of computer scientists

and computer engineers who tackle research that is connected to the development of intelligent traffic and transportation systems. It is also possible to see that this community is growing, and that research projects are getting more and more interdisciplinary. To foster the cooperation among the involved communities, this book aims at giving a broad introduction into the basic but relevant concepts related to transportation systems, targeting researchers and practitioners from computer science and

information technology. In addition, the second part of the book gives a panorama of some of the most exciting and newest technologies, originating in computer science and computer engineering, that are now being employed in projects related to car-to-car communication, interconnected vehicles, car navigation, platooning, crowd sensing and sensor networks, among others. This material will also be of interest to engineers and researchers from the traffic and transportation community. This is the first comprehensive introduction

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**to multiagent systems and contemporary
distributed artificial intelligence that is
suitable as a textbook.**

**Creating Autonomous Vehicle Systems,
Second Edition**

**Soft Computing and Intelligent Systems
Intelligent Systems in Process Engineering,
Part II: Paradigms from Process Operations
Intelligent Autonomous Systems**

**Human Performance in Automated and
Autonomous Systems, Two-Volume Set
Encyclopedia of Information Science and
Technology, Second Edition**

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The field of soft computing is emerging from the cutting edge research over the last ten years devoted to fuzzy engineering and genetic algorithms. The subject is being called soft computing and computational intelligence. With acceptance of the research fundamentals in these important areas, the field is expanding into direct applications through engineering and systems science. This book cover the fundamentals of this emerging filed, as well as direct applications and case studies. There is a need for practicing engineers, computer scientists, and system scientists to directly apply "fuzzy" engineering into a wide array of devices and systems.

This volume explores the intersection of robust

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intelligence (RI) and trust in autonomous systems across multiple contexts among autonomous hybrid systems, where hybrids are arbitrary combinations of humans, machines and robots. To better understand the relationships between artificial intelligence (AI) and RI in a way that promotes trust between autonomous systems and human users, this book explores the underlying theory, mathematics, computational models, and field applications. It uniquely unifies the fields of RI and trust and frames it in a broader context, namely the effective integration of human-autonomous systems. A description of the current state of the art in RI and trust introduces the research work in this area. With this foundation, the

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chapters further elaborate on key research areas and gaps that are at the heart of effective human-systems integration, including workload management, human computer interfaces, team integration and performance, advanced analytics, behavior modeling, training, and, lastly, test and evaluation. Written by international leading researchers from across the field of autonomous systems research, Robust Intelligence and Trust in Autonomous Systems dedicates itself to thoroughly examining the challenges and trends of systems that exhibit RI, the fundamental implications of RI in developing trusted relationships with present and future autonomous systems, and the effective human systems integration that must result for trust

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to be sustained. Contributing authors: David W. Aha, Jenny Burke, Joseph Coyne, M.L. Cummings, Munjal Desai, Michael Drinkwater, Jill L. Drury, Michael W. Floyd, Fei Gao, Vladimir Gontar, Ayanna M. Howard, Mo Jamshidi, W.F. Lawless, Kapil Madathil, Ranjeev Mittu, Arezou Moussavi, Gari Palmer, Paul Robinette, Behzad Sadrfaridpour, Hamed Saeidi, Kristin E. Schaefer, Anne Selwyn, Ciara Sibley, Donald A. Sofge, Erin Solovey, Aaron Steinfeld, Barney Tannahill, Gavin Taylor, Alan R. Wagner, Yue Wang, Holly A. Yanco, Dan Zwillinger.

This volume contains the papers presented at the International Workshop Autonomous Intelligent Systems: Agents and Data Mining (AIS-ADM 2005)

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held in St. Petersburg, Russia, during June 6-8, 2005. Rights of robots, a closer collaboration between law and the health sector, the relation between justice and development - these are some of the topics covered in The Law of the Future and the Future of Law: Volume II. The central question is: how will law evolve in the coming years? This book gives you a rich array of visions on current legal trends. The readable think pieces offer indications of law's cutting edge. The book brings new material that is not available in the first volume of The Law of the Future and the Future of Law, published in June 2011. Among the authors in this volume are William Twining (Emeritus Quain Professor of Jurisprudence, University

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College London), David Eagleman (Director, Initiative on Neuroscience and Law), Hassane Cisse (Deputy General Counsel, The World Bank), Gabrielle Marceau (Counsellor, World Trade Organisation), Benjamin Odoki (Chief Justice, Republic of Uganda), Martijn W. Scheltema (Attorney at law, Pels Rijcken and Droogleever Fortuijn), Austin Onuoha (Founder, The Africa Centre for Corporate Responsibility), Lokke Moerel (Partner, De Brauw Blackstone Westbroek), S.I. Strong (Senior Fellow, Center for the Study of Dispute Resolution), Jan M. Smits (Chair of European Private Law, Maastricht University).

27th International Conference on Industrial Engineering and Other Applications of Applied

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*Intelligent Systems, IEA/AIE 2014, Kaohsiung, Taiwan,
June 3-6, 2014, Proceedings, Part I*

Aspects, Motivations, and Methods

Intelligent Systems for Science and Information

Third International Conference, ICAIS 2014,

Bournemouth, UK, September 8-9, 2014. Proceedings

The Art of Agent-oriented Modeling

Human-Centered AI

This book gathers recent research work on emerging Artificial Intelligence (AI) methods for processing and storing data generated by cloud-based Internet of Things (IoT) infrastructures. Major topics

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covered include the analysis and development of AI-powered mechanisms in future IoT applications and architectures. Further, the book addresses new technological developments, current research trends, and industry needs. Presenting case studies, experience and evaluation reports, and best practices in utilizing AI applications in IoT networks, it strikes a good balance between theoretical and practical issues. It also provides technical/scientific information on various aspects of AI technologies,

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ranging from basic concepts to research grade material, including future directions. The book is intended for researchers, practitioners, engineers and scientists involved in the design and development of protocols and AI applications for IoT-related devices. As the book covers a wide range of mobile applications and scenarios where IoT technologies can be applied, it also offers an essential introduction to the field.

This book is a collection of selected

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papers presented at the Second Congress on Intelligent Systems (CIS 2021), organized by Soft Computing Research Society and CHRIST (Deemed to be University), Bengaluru, India during September 4 - 5, 2021. It includes novel and innovative work from experts, practitioners, scientists and decision-makers from academia and industry. It covers topics such as Internet of Things, information security, embedded systems, real-time systems, cloud computing, big data analysis, quantum computing, automation

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systems, bio-inspired intelligence, cognitive systems, cyber physical systems, data analytics, data/web mining, data science, intelligence for security, intelligent decision making systems, intelligent information processing, intelligent transportation, artificial intelligence for machine vision, imaging sensors technology, image segmentation, convolutional neural network, image/video classification, soft computing for machine vision, pattern recognition, human computer interaction, robotic devices and

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systems, autonomous vehicles, intelligent control systems, human motor control, game playing, evolutionary algorithms, swarm optimization, neural network, deep learning, supervised learning, unsupervised learning, fuzzy logic, rough sets, computational optimization, and neuro fuzzy systems.

The presentations of the invited speakers and authors mainly focused on developing and studying new methods to cope with the problems posed by real-life applications of artificial intelligence. Papers presented in the

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etwentythirdconferenceinthseriescovered theories as well as applications of intelligent systems in solving complex real-life problems. We received 297 papers for the main track, selecting 119 of them with the highest quality standards. Each paper was revised by at least three members of the Program Committee. This research book contains a sample of most recent research in the area of intelligent autonomous systems. The contributions include: General aspects of intelligent autonomous systems Design of

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intelligent autonomous robots Biped robots
Robot for stair-case navigation Ensemble
learning for multi-source information
fusion Intelligent autonomous systems in
psychiatry Condition monitoring of
internal combustion engine Security
management of an enterprise network High
dimensional neural nets and applications
This book is directed to engineers,
scientists, professor and the
undergraduate/postgraduate students who
wish to explore this field further.
With an Introduction to Machine Learning,

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Second Edition

Research Handbook on the Law of Artificial
Intelligence

Extended and Selected Results from the
Science and Information Conference 2013

Introduction to Intelligent Systems in
Traffic and Transportation

Planning in Intelligent Systems

Progress in Artificial Intelligence

***Digital systems that bring together the computing
capacity for processing large bodies of information with
the human cognitive capability are called intelligent***

systems. Building these systems has become one of the great goals of modern technology. This goal has both intellectual and economic incentives. The need for such intelligent systems has become more intense in the face of the global connectivity of the internet. There has become an almost insatiable requirement for instantaneous information and decision brought about by this confluence of computing and communication. This requirement can only be satisfied by the construction of innovative intelligent systems. A second and perhaps an even more significant development is the great advances being made in genetics and related areas

of biotechnology. Future developments in biotechnology may open the possibility for the development of a true human-silicon interaction at the micro level, neural and cellular, bringing about a need for "intelligent" systems. What is needed to further the development of intelligent systems are tools to enable the representation of human cognition in a manner that allows formal manipulation. The idea of developing such an algebra goes back to Leibniz in the 17th century with his dream of a calculus ratiocinator. It wasn't until two hundred years later beginning with the work of Boole, Cantor and Frege that a formal mathematical logic for modeling human

reasoning was developed. The introduction of the modern digital computer during the Second World War by von Neumann and others was a culmination of this intellectual trend.

This book is a collection of selected papers presented at the Second Congress on Intelligent Systems (CIS 2021), organized by Soft Computing Research Society and CHRIST (Deemed to be University), Bengaluru, India, during September 4 – 5, 2021. It includes novel and innovative work from experts, practitioners, scientists, and decision-makers from academia and industry. It covers topics such as Internet of things, information

security, embedded systems, real-time systems, cloud computing, big data analysis, quantum computing, automation systems, bio-inspired intelligence, cognitive systems, cyber physical systems, data analytics, data/web mining, data science, intelligence for security, intelligent decision making systems, intelligent information processing, intelligent transportation, artificial intelligence for machine vision, imaging sensors technology, image segmentation, convolutional neural network, image/video classification, soft computing for machine vision, pattern recognition, human–computer interaction, robotic devices and systems, autonomous

vehicles, intelligent control systems, human motor control, game playing, evolutionary algorithms, swarm optimization, neural network, deep learning, supervised learning, unsupervised learning, fuzzy logic, rough sets, computational optimization, and neuro-fuzzy systems. This book is one of the first technical overviews of autonomous vehicles written for a general computing and engineering audience. The authors share their practical experiences designing autonomous vehicle systems. These systems are complex, consisting of three major subsystems: (1) algorithms for localization, perception, and planning and control; (2) client systems,

such as the robotics operating system and hardware platform; and (3) the cloud platform, which includes data storage, simulation, high-definition (HD) mapping, and deep learning model training. The algorithm subsystem extracts meaningful information from sensor raw data to understand its environment and make decisions as to its future actions. The client subsystem integrates these algorithms to meet real-time and reliability requirements. The cloud platform provides offline computing and storage capabilities for autonomous vehicles. Using the cloud platform, new algorithms can be tested so as to update the HD map—in

addition to training better recognition, tracking, and decision models. Since the first edition of this book was released, many universities have adopted it in their autonomous driving classes, and the authors received many helpful comments and feedback from readers. Based on this, the second edition was improved by extending and rewriting multiple chapters and adding two commercial test case studies. In addition, a new section entitled “Teaching and Learning from this Book” was added to help instructors better utilize this book in their classes. The second edition captures the latest advances in autonomous driving and that it also

presents usable real-world case studies to help readers better understand how to utilize their lessons in commercial autonomous driving projects. This book should be useful to students, researchers, and practitioners alike. Whether you are an undergraduate or a graduate student interested in autonomous driving, you will find herein a comprehensive overview of the whole autonomous vehicle technology stack. If you are an autonomous driving practitioner, the many practical techniques introduced in this book will be of interest to you. Researchers will also find extensive references for an effective, deeper exploration of the various

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technologies.

The two volume set LNAI 8481 and 8482 constitutes the refereed conference proceedings of the 27th International Conference on Industrial, Engineering and Other Applications of Applied Intelligent Systems, IEA/AIE 2014, held in Kaohsiung, Taiwan, in June 2014. The total of 106 papers selected for the proceedings were carefully reviewed and selected from various submissions. The papers deal with a wide range of topics from applications of applied intelligent systems to solve real-life problems in all areas including engineering, science, industry, automation and robotics,

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*business and finance, medicine and biomedicine,
bioinformatics, cyberspace and human-machine
interaction.*

Volume II

*No Mere Deodands: Human Responsibilities in the Use
of Violent Intelligent Systems Under Public
International Law*

*Introduction to Autonomous Mobile Robots, second
edition*

*Recent Advances in Intelligent Paradigms and
Applications*

Foundations and Applications

Theories, Methods, and Technologies

This two-volume set addresses a variety of human factors issues and engineering concerns across various real-world applications such as aviation and driving, cybersecurity, and healthcare systems. The contents of these books also present recent theories and methods related to human performance, workload and usability assessment in automated and autonomous systems. In this set, the authors discuss both current and developing topics of advanced automation technologies and present emerging practical challenges. Topics covered include unmanned aerial systems and self-

driving cars, individual and team performance, human-robot interaction, and operator selection and training. Both practical and theoretical discussions of modern automated and autonomous systems are provided throughout each of the volumes. These books are suitable for those first approaching the issues to those well versed in these fast-moving areas, including students, teachers, researchers, engineers, and policy makers alike. Volume 1 - Human Performance in Automated and Autonomous Systems: Current Theory and Methods Volume 2 - Human Performance in Automated and Autonomous Systems: Emerging

Issues and Practical Perspectives

This book establishes the foundations needed to realize the ultimate goals for artificial intelligence, such as autonomy and trustworthiness. Aimed at scientists, researchers, technologists, practitioners, and students, it brings together contributions offering the basics, the challenges and the state-of-the-art on trusted autonomous systems in a single volume. The book is structured in three parts, with chapters written by eminent researchers and outstanding practitioners and users in the field. The first part covers foundational artificial intelligence technologies, while

the second part covers philosophical, practical and technological perspectives on trust. Lastly, the third part presents advanced topics necessary to create future trusted autonomous systems. The book augments theory with real-world applications including cyber security, defence and space.

This book covers advances in system, control and computing. This book gathers selected high-quality research papers presented at the International Conference on Advances in Systems, Control and Computing (AISCC 2020), held at MNIT Jaipur during February 27–28, 2020. The first part is

advances in systems and it is dedicated to applications of the artificial neural networks, evolutionary computation, swarm intelligence, artificial immune systems, fuzzy system, autonomous and multi-agent systems, machine learning, other intelligent systems and related areas. In the second part, machine learning and other intelligent algorithms for design of control/control analysis are covered. The last part covers advancements, modifications, improvements and applications of intelligent algorithms.

The field of artificial intelligence (AI) has made tremendous advances in the last two decades, but as

smart as AI is now, it is getting smarter and becoming more autonomous. This raises a host of challenges to current legal doctrine, including whether AI/algorithms should count as ‘speech’, whether AI should be regulated under antitrust and criminal law statutes, and whether AI should be considered as an agent under agency law or be held responsible for injuries under tort law. This book contains chapters from US and international law scholars on the role of law in an age of increasingly smart AI, addressing these and other issues that are critical to the evolution of the field.

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**Advances in Intelligent Systems and Computing II
Foundations of Trusted Autonomy**

Intelligent Systems and Networks

Creating Autonomous Vehicle Systems

**12th Portuguese Conference on Artificial Intelligence,
EPIA 2005, Covilha, Portugal, December 5-8, 2005,
Proceedings**

Trends in Applied Intelligent Systems

*The first edition of this popular
textbook, Contemporary Artificial
Intelligence, provided an accessible
and student friendly introduction to*

AI. This fully revised and expanded update, Artificial Intelligence: With an Introduction to Machine Learning, Second Edition, retains the same accessibility and problem-solving approach, while providing new material and methods. The book is divided into five sections that focus on the most useful techniques that have emerged from AI. The first section of the book covers logic-based methods, while the second section focuses on probability-

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based methods. Emergent intelligence is featured in the third section and explores evolutionary computation and methods based on swarm intelligence. The newest section comes next and provides a detailed overview of neural networks and deep learning. The final section of the book focuses on natural language understanding. Suitable for undergraduate and beginning graduate students, this class-tested textbook provides students and other readers

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with key AI methods and algorithms for solving challenging problems involving systems that behave intelligently in specialized domains such as medical and software diagnostics, financial decision making, speech and text recognition, genetic analysis, and more.

The book Intelligent Systems for Science and Information is the remarkable collection of extended chapters from the selected papers that

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were published in the proceedings of Science and Information (SAI) Conference 2013. It contains twenty-four chapters in the field of Intelligent Systems, which received highly recommended feedback during SAI Conference 2013 review process. All chapters have gone through substantial extension and consolidation and were subject to another round of rigorous review and additional modification. These chapters represent the state of

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the art of the cutting-edge research and technologies in related areas, and can help inform relevant research communities and individuals of the future development in Science and Information.

The remarkable progress in algorithms for machine and deep learning have opened the doors to new opportunities, and some dark possibilities. However, a bright future awaits those who build on their working methods by including HCAI

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strategies of design and testing. As many technology companies and thought leaders have argued, the goal is not to replace people, but to empower them by making design choices that give humans control over technology. In Human-Centered AI, Professor Ben Shneiderman offers an optimistic realist's guide to how artificial intelligence can be used to augment and enhance humans' lives. This project bridges the gap between ethical considerations and practical

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realities to offer a road map for successful, reliable systems. Digital cameras, communications services, and navigation apps are just the beginning. Shneiderman shows how future applications will support health and wellness, improve education, accelerate business, and connect people in reliable, safe, and trustworthy ways that respect human values, rights, justice, and dignity. A comprehensive survey of artificial

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intelligence algorithms and programming organization for robot systems, combining theoretical rigor and practical applications. This textbook offers a comprehensive survey of artificial intelligence (AI) algorithms and programming organization for robot systems. Readers who master the topics covered will be able to design and evaluate an artificially intelligent robot for applications involving sensing, acting, planning, and

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learning. A background in AI is not required; the book introduces key AI topics from all AI subdisciplines throughout the book and explains how they contribute to autonomous capabilities. This second edition is a major expansion and reorganization of the first edition, reflecting the dramatic advances made in AI over the past fifteen years. An introductory overview provides a framework for thinking about AI for robotics,

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distinguishing between the fundamentally different design paradigms of automation and autonomy. The book then discusses the reactive functionality of sensing and acting in AI robotics; introduces the deliberative functions most often associated with intelligence and the capability of autonomous initiative; surveys multi-robot systems and (in a new chapter) human-robot interaction; and offers a “metaview” of how to

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design and evaluate autonomous systems and the ethical considerations in doing so. New material covers locomotion, simultaneous localization and mapping, human-robot interaction, machine learning, and ethics. Each chapter includes exercises, and many chapters provide case studies. Endnotes point to additional reading, highlight advanced topics, and offer robot trivia.

Congress on Intelligent Systems

The 1994 Goddard Conference on Space

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*Applications of Artificial Intelligence
Robust Intelligence and Trust in
Autonomous Systems*

*Second International Conference, ICAIS
2011, Klagenfurt, Austria, September
6-8, 2011, Proceedings*

*Applications of Advanced Computing in
Systems*

Proceedings of CIS 2021, Volume 2

*This book constitutes the refereed proceedings of the
Second International Workshop on Autonomous Intelligent
Systems: Agents and Data Mining, AIS-ADM 2007, held in St.*

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Petersburg, Russia in June 2007. The 17 revised full papers and six revised short papers presented together with four invited lectures cover agent and data mining, agent competition and data mining, as well as text mining, semantic Web, and agents.

This book constitutes the proceedings of the International Conference on Adaptive and Intelligent Systems, ICAIS 2014, held in Bournemouth, UK, in September 2014. The 19 full papers included in these proceedings together with the abstracts of 4 invited talks, were carefully reviewed and selected from 32 submissions. The contributions are organized under the following topical sections: advances in feature selection; clustering and classification; adaptive optimization; advances in time series analysis.

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*The first comparative examination of planning paradigms This text begins with the principle that the ability to anticipate and plan is an essential feature of intelligent systems, whether human or machine. It further assumes that better planning results in greater achievements. With these principles as a foundation, Planning in Intelligent Systems provides readers with the tools needed to better understand the process of planning and to become better planners themselves. The text is divided into two parts: * Part One, "Theoretical," discusses the predominant schools of thought in planning: psychology and cognitive science, organizational science, computer science, mathematics, artificial intelligence, and systems theory. In particular, the book examines commonalities and differences*

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*among the goals, methods, and techniques of these various approaches to planning. The result is a better understanding of the process of planning through the cross-fertilization of ideas. Each chapter contains a short introduction that sets forth the interrelationships of that chapter to the main ideas featured in the other chapters. * Part Two, "Practical," features six chapters that center on a case study of The Netherlands Railways. Readers learn to apply theory to a real-world situation and discover how expanding their repertoire of planning methods can help solve seemingly intractable problems. All chapters have been contributed by leading experts in the various schools of planning and carefully edited to ensure a consistent high standard throughout. This book is designed to not only*

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expand the range of planning tools used, but also to enable readers to use them more effectively. It challenges readers to look at new approaches and learn from new schools of thought. Planning in Intelligent Systems delivers effective planning approaches for researchers, professors, students, and practitioners in artificial intelligence, computer science, cognitive psychology, and mathematics, as well as industry planners and managers.

The new edition of an introduction to multiagent systems that captures the state of the art in both theory and practice, suitable as textbook or reference. Multiagent systems are made up of multiple interacting intelligent agents—computational entities to some degree autonomous and able to cooperate, compete, communicate, act flexibly,

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and exercise control over their behavior within the frame of their objectives. They are the enabling technology for a wide range of advanced applications relying on distributed and parallel processing of data, information, and knowledge relevant in domains ranging from industrial manufacturing to e-commerce to health care. This book offers a state-of-the-art introduction to multiagent systems, covering the field in both breadth and depth, and treating both theory and practice. It is suitable for classroom use or independent study. This second edition has been completely revised, capturing the tremendous developments in multiagent systems since the first edition appeared in 1999. Sixteen of the book's seventeen chapters were written for this edition; all chapters are by leaders in the field, with each author

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contributing to the broad base of knowledge and experience on which the book rests. The book covers basic concepts of computational agency from the perspective of both individual agents and agent organizations; communication among agents; coordination among agents; distributed cognition; development and engineering of multiagent systems; and background knowledge in logics and game theory. Each chapter includes references, many illustrations and examples, and exercises of varying degrees of difficulty. The chapters and the overall book are designed to be self-contained and understandable without additional material. Supplemental resources are available on the book's Web site. Contributors Rafael Bordini, Felix Brandt, Amit Chopra, Vincent Conitzer, Virginia Dignum, Jürgen Dix,

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*Ed Durfee, Edith Elkind, Ulle Endriss, Alessandro Farinelli,
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Leyton-Brown, Evangelos Markakis, Lin Padgham, Julian
Padget, Iyad Rahwan, Talal Rahwan, Alex Rogers, Jordi
Sabater-Mir, Yoav Shoham, Munindar P. Singh, Kagan
Tumer, Karl Tuyls, Wiebe van der Hoek, Laurent Vercouter,
Meritxell Vinyals, Michael Winikoff, Michael Wooldridge,
Shlomo Zilberstein*

Multiagent Systems, second edition

International Workshop, AIS-ADM 2005

*Proceedings of International Conference on Advances in
Systems, Control and Computing*

Theory and Applications

Artificial intelligence - When do machines take over?

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Multiagent Systems

This book is the first technical overview of autonomous vehicles written for a general computing and engineering audience. The authors share their practical experiences of creating autonomous vehicle systems. These systems are complex, consisting of three major subsystems: (1) algorithms for localization, perception, and planning and control; (2) client systems, such as the robotics operating system and hardware platform; and (3) the cloud platform, which includes data storage, simulation, high-definition (HD) mapping, and deep learning model training. The algorithm subsystem extracts meaningful information from sensor raw data to understand its environment and make decisions about its actions. The client subsystem integrates these algorithms to meet real-time and reliability requirements. The cloud platform provides offline computing and storage capabilities for

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autonomous vehicles. Using the cloud platform, we are able to test new algorithms and update the HD map—plus, train better recognition, tracking, and decision models. This book consists of nine chapters. Chapter 1 provides an overview of autonomous vehicle systems; Chapter 2 focuses on localization technologies; Chapter 3 discusses traditional techniques used for perception; Chapter 4 discusses deep learning based techniques for perception; Chapter 5 introduces the planning and control sub-system, especially prediction and routing technologies; Chapter 6 focuses on motion planning and feedback control of the planning and control subsystem; Chapter 7 introduces reinforcement learning-based planning and control; Chapter 8 delves into the details of client systems design; and Chapter 9 provides the details of cloud platforms for autonomous driving. This book should be useful to students, researchers, and practitioners alike. Whether you

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are an undergraduate or a graduate student interested in autonomous driving, you will find herein a comprehensive overview of the whole autonomous vehicle technology stack. If you are an autonomous driving practitioner, the many practical techniques introduced in this book will be of interest to you. Researchers will also find plenty of references for an effective, deeper exploration of the various technologies.

This book constitutes the refereed proceedings of the Second International Conference on Autonomous and Intelligent Systems, AIS 2011, held in Burnaby, BC, Canada, in June 2011, colocated with the International Conference on Image Analysis and Recognition, IACIAR 2011. The 40 revised full papers presented were carefully reviewed and selected from 62 submissions. The papers are organized in topical sections on autonomous and intelligent systems, intelligent and

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advanced control systems, intelligent sensing and data analysis, human-machine interaction, and intelligent circuit analysis and signal processing.

This book reports on new theories and applications in the field of intelligent systems and computing. It covers computational and artificial intelligence methods, as well as advances in computer vision, current issues in big data and cloud computing, computation linguistics, and cyber-physical systems. It also reports on data mining and knowledge extraction technologies, as well as central issues in intelligent information management. Written by active researchers, the respective chapters are based on papers presented at the International Conference on Computer Science and Information Technologies (CSIT 2017), held on September 5–8, 2017, in Lviv, Ukraine; and at two workshops accompanying the conference: one on inductive modeling,

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jointly organized by the Lviv Polytechnic National University and the National Academy of Science of Ukraine; and another on project management, which was jointly organized by the Lviv Polytechnic National University, the International Project Management Association, the Ukrainian Project Management Association, the Kazakhstan Project Management Association, and Nazarbayev University. Given its breadth of coverage, the book provides academics and professionals with extensive information and a timely snapshot of the field of intelligent systems, and is sure to foster new discussions and collaborations among different groups.

Volumes 21 and 22 of Advances in Chemical Engineering contain ten prototypical paradigms which integrate ideas and methodologies from artificial intelligence with those from operations research, estimation and control theory, and statistics. Each paradigm has been constructed

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around an engineering problem, e.g. product design, process design, process operations monitoring, planning, scheduling, or control. Along with the engineering problem, each paradigm advances a specific methodological theme from AI, such as: modeling languages; automation in design; symbolic and quantitative reasoning; inductive and deductive reasoning; searching spaces of discrete solutions; non-monotonic reasoning; analogical learning; empirical learning through neural networks; reasoning in time; and logic in numerical computing. Together the ten paradigms of the two volumes indicate how computers can expand the scope, type, and amount of knowledge that can be articulated and used in solving a broad range of engineering problems. Sets the foundations for the development of computer-aided tools for solving a number of distinct engineering problems Exposes the reader to a variety of AI techniques in automatic modeling,

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*searching, reasoning, and learning The product of ten-years
experience in integrating AI into process engineering Offers expanded
and realistic formulations of real-world problems*

*Second International Workshop, AIS-ADM 2007, St. Petersburg,
Russia, June 3-5, 2007, Proceedings*

Adaptive and Intelligent Systems

Proceedings of CIS 2021, Volume 1

*Selected Papers from the International Conference on Computer
Science and Information Technologies, CSIT 2017, September 5-8
Lviv, Ukraine*

The Law of the Future and the Future of Law

Autonomous Intelligent Systems: Agents and Data Mining

A comprehensive introduction to new approaches in artificial
intelligence and robotics that are inspired by self-organizing

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biological processes and structures. New approaches to artificial intelligence spring from the idea that intelligence emerges as much from cells, bodies, and societies as it does from evolution, development, and learning. Traditionally, artificial intelligence has been concerned with reproducing the abilities of human brains; newer approaches take inspiration from a wider range of biological structures that are capable of autonomous self-organization. Examples of these new approaches include evolutionary computation and evolutionary electronics, artificial neural networks, immune systems, biorobotics, and swarm intelligence, to mention only a few. This book offers a comprehensive introduction to the emerging field of biologically inspired artificial intelligence that can be used as an upper-level text or as a reference for researchers. Each chapter presents computational approaches

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inspired by a different biological system; each begins with background information about the biological system and then proceeds to develop computational models that make use of biological concepts. The chapters cover evolutionary computation and electronics; cellular systems; neural systems, including neuromorphic engineering; developmental systems; immune systems; behavioral systems—including several approaches to robotics, including behavior-based, bio-mimetic, epigenetic, and evolutionary robots; and collective systems, including swarm robotics as well as cooperative and competitive co-evolving systems. Chapters end with a concluding overview and suggest reading.

This book constitutes the proceedings of the International Conference on Adaptive and Intelligent Systems, ICAIS 2011, held

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in Klagenfurt, Austria, in September 2011. The 36 full papers included in these proceedings together with the abstracts of 4 invited talks, were carefully reviewed and selected from 72 submissions. The contributions are organized under the following topical sections: incremental learning; adaptive system architecture; intelligent system engineering; data mining and pattern recognition; intelligent agents; and computational intelligence.

Bio-Inspired Artificial Intelligence

Artificial Intelligence

Second International Conference, AIS 2011, Burnaby, BC, Canada

June 22-24, 2011, Proceedings

Selected Articles from ICISN 2022, Vietnam